



MAORY Presentation

6-7 / 02 / 2020

Zoltán Hubert, Philippe Feautrier, Jean-Jacques Correia,
François Hénault, Sylvain Douté, Patrick Rabou



MPIA – MAORY Presentation



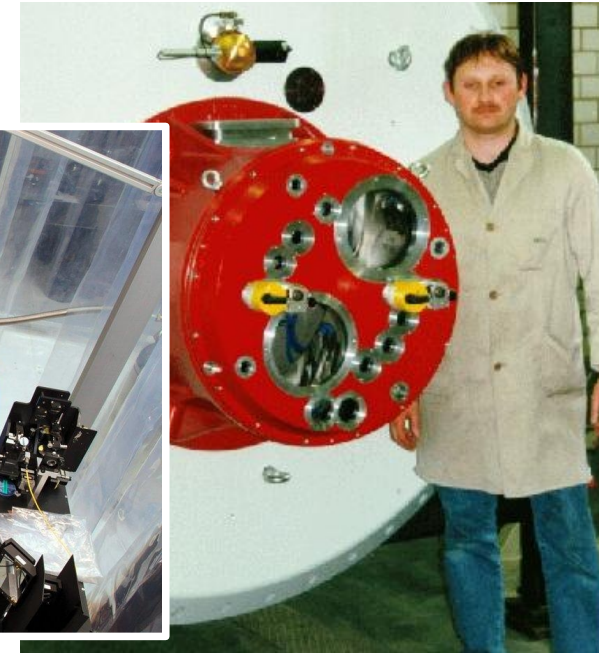
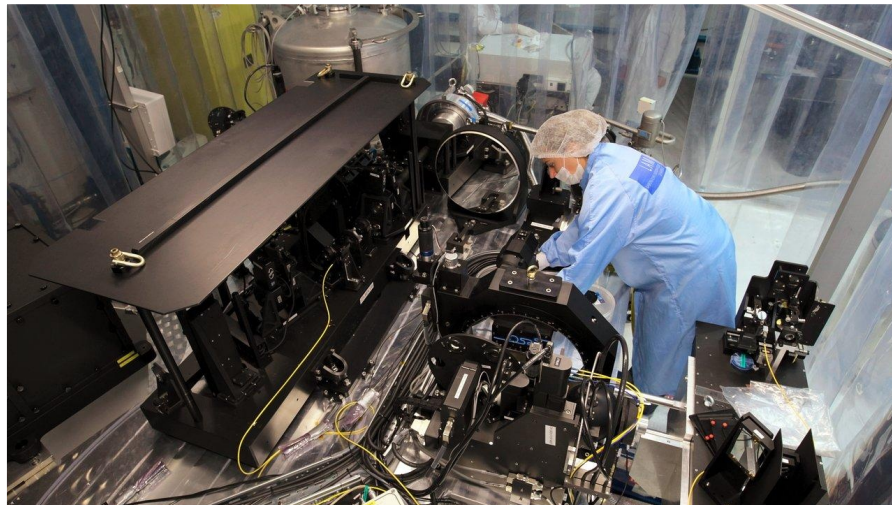
- MCAO presentation
- MAORY optical design history
- LGS-WFS module

What is MCAO ?



- Adaptive Optics: a little history

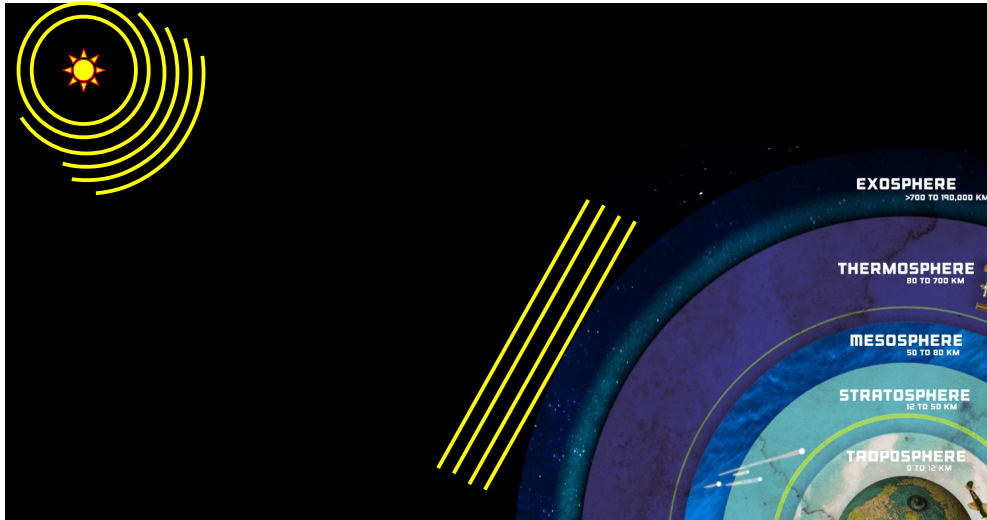
- First civil use: prototype COME-ON, end-of the 80'
- First scientific instrument: ADONIS @ ESO LaSilla in 1991
- NAOS – CONICA @ VLT: First light in 2001, decommissioned on 1st October 2019
- SPHERE @VLT in 2014
- 4×CIAO @VLTI in 2016
- MICADO @ELT in 2022?



What is MCAO ?



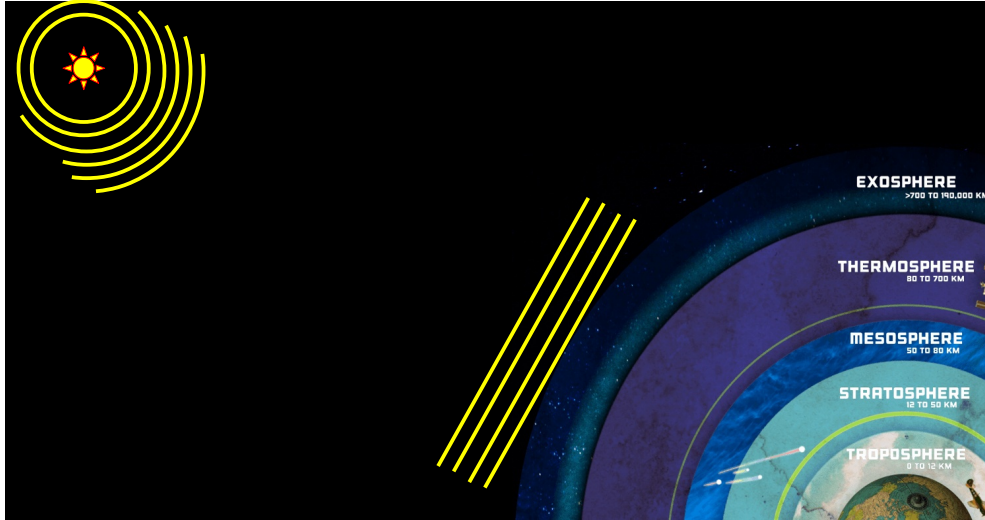
- Adaptive Optics: what is it ?



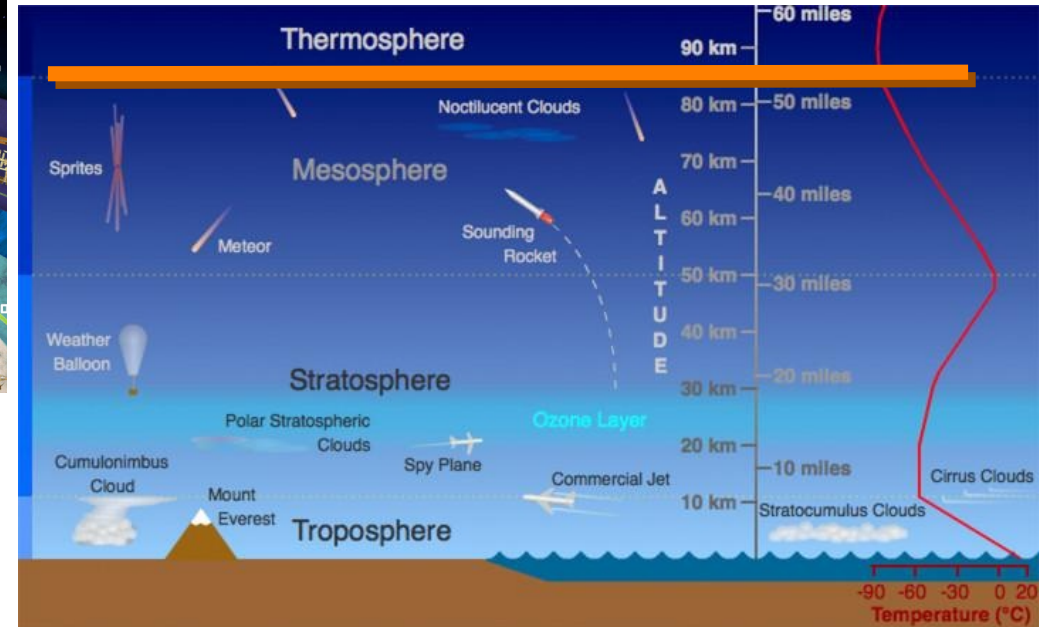
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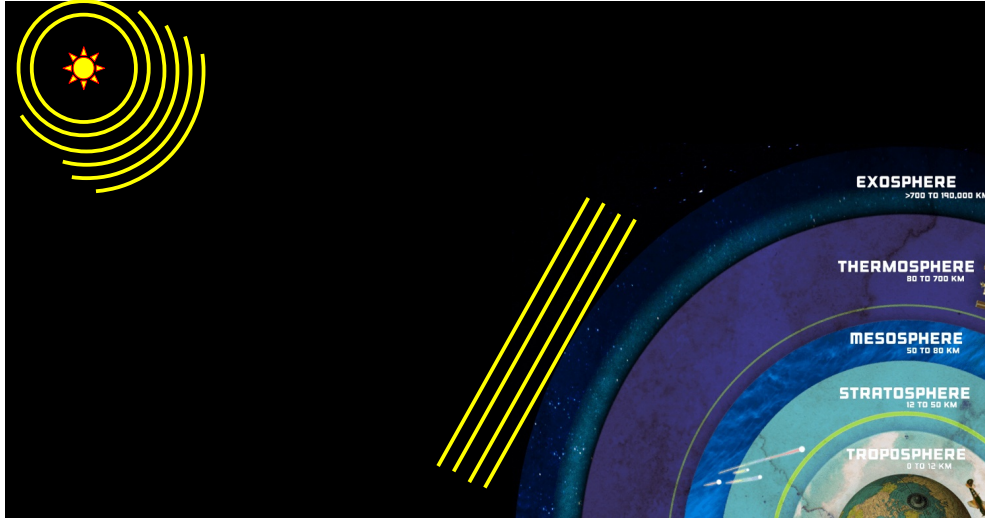
Von Kármán limit: 100km
Sodium layer: 85km



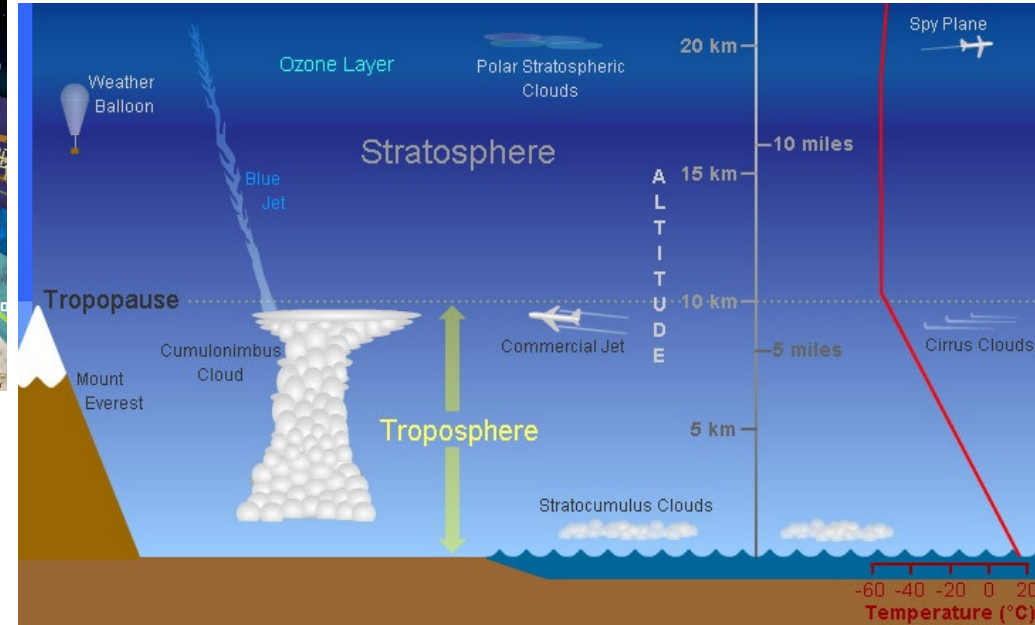
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- Adaptive Optics: what is it ?



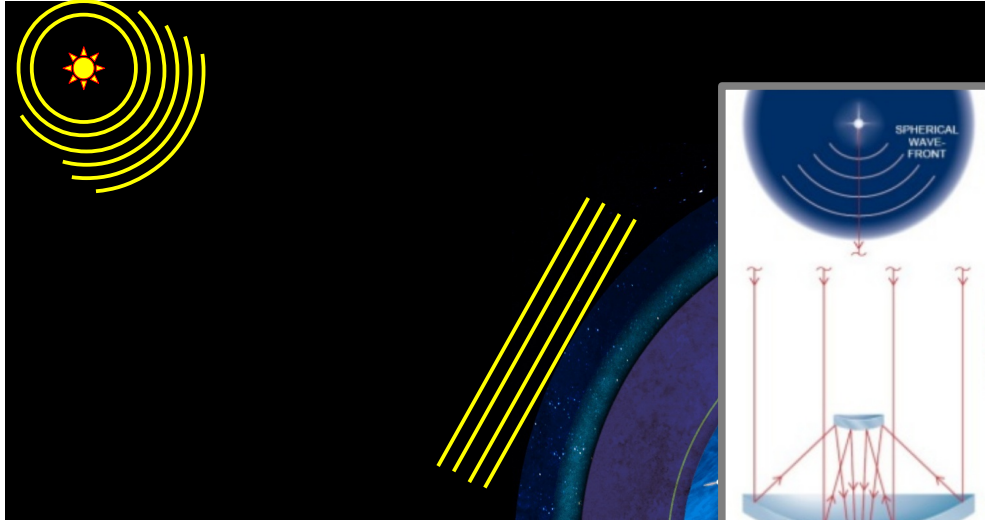
Refraction index of air is T° and P dependent



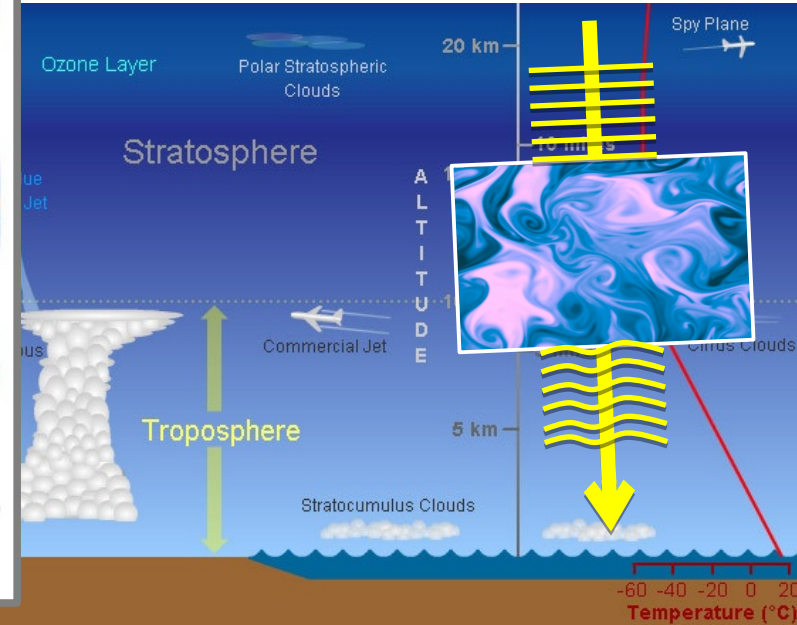
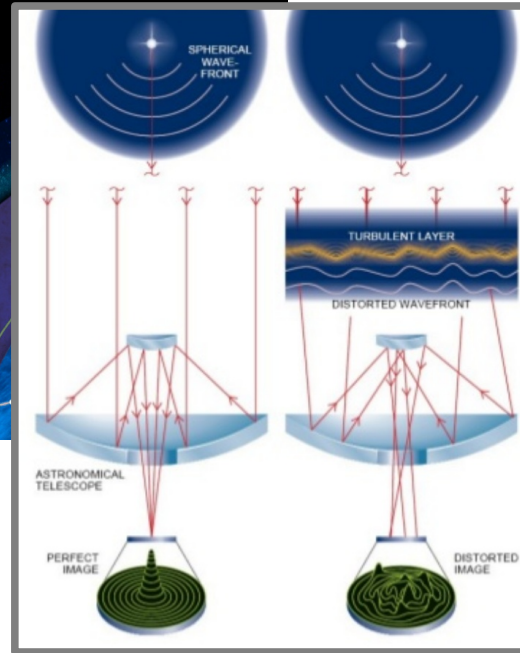
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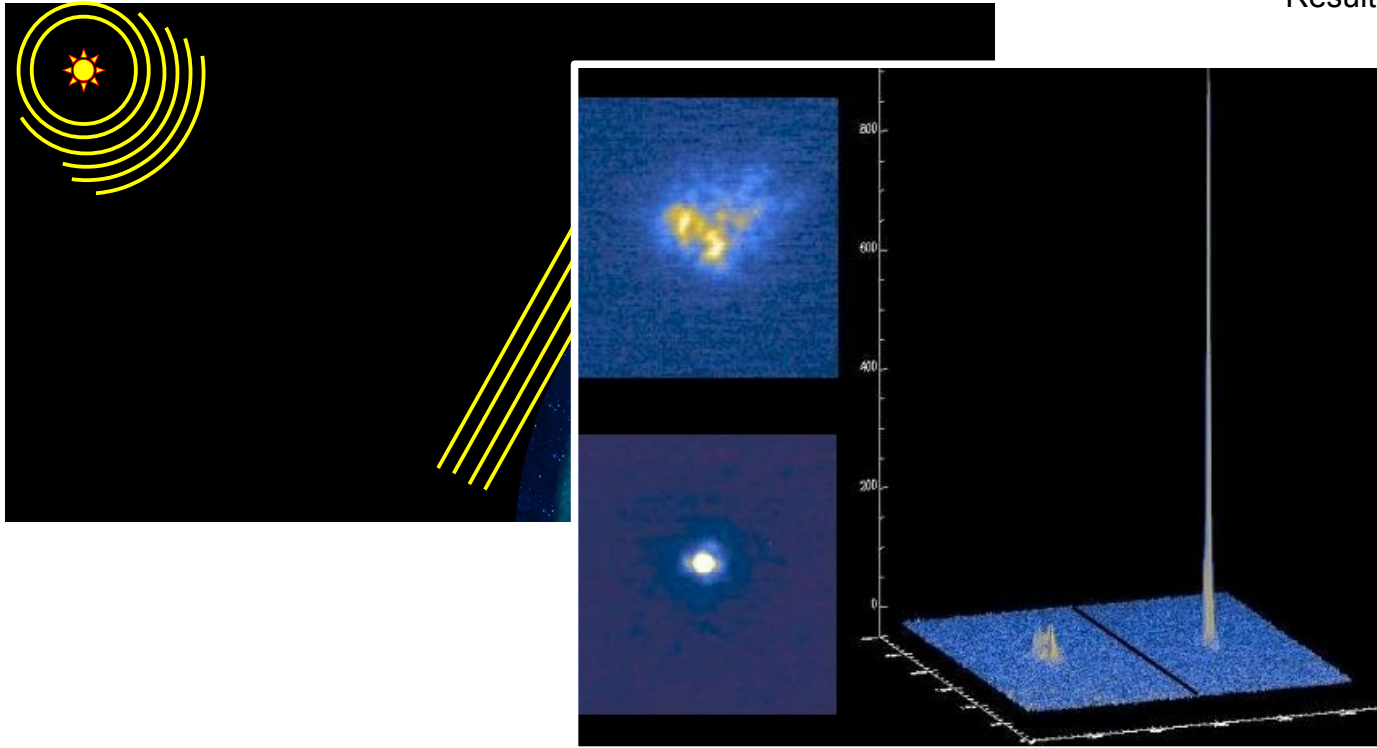
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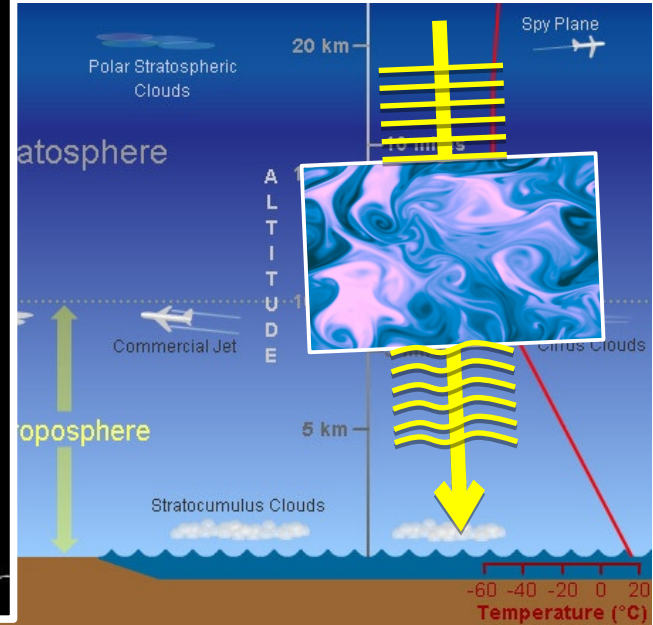
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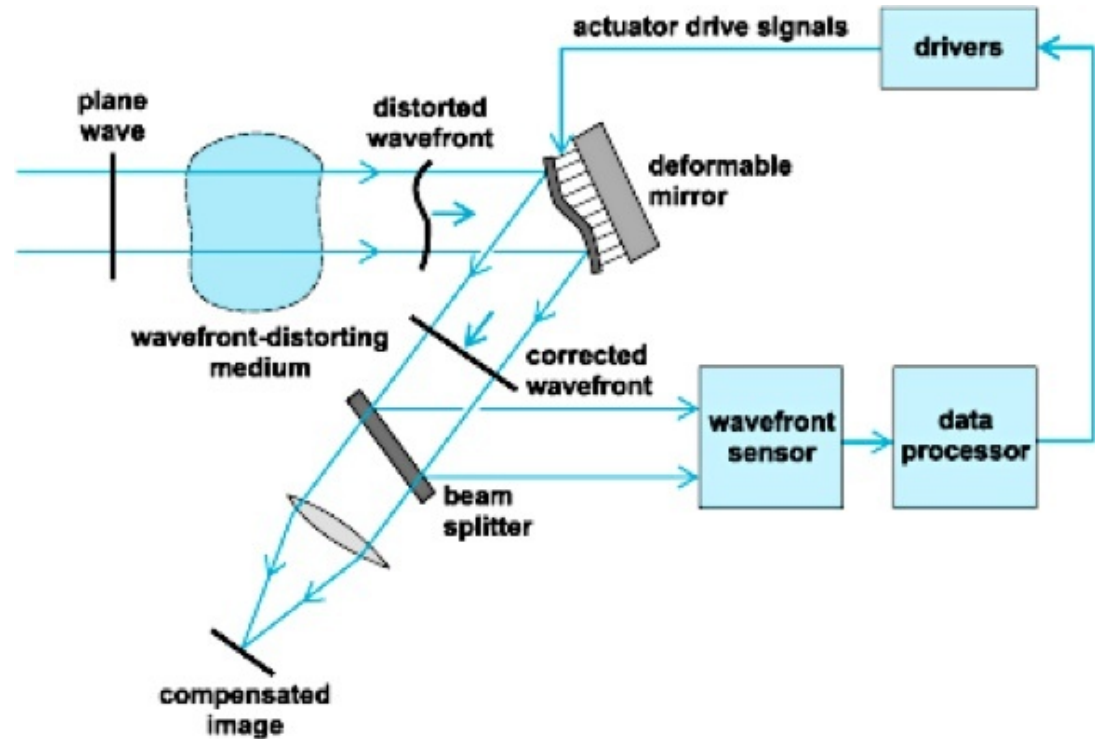
Result: "seeing" limited images



What is MCAO ?

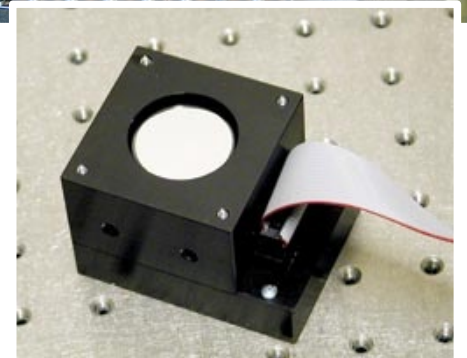
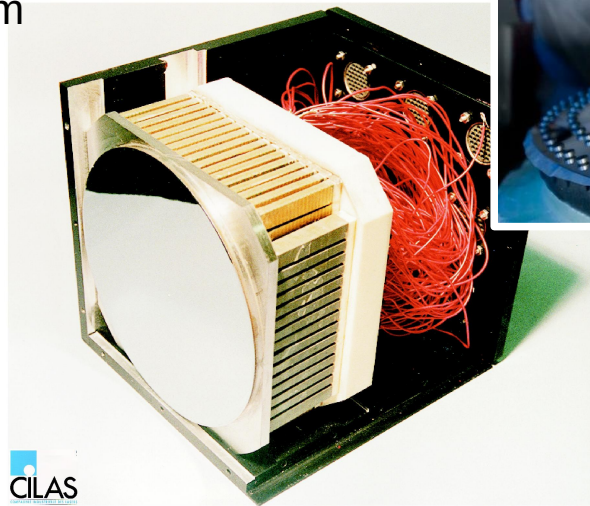
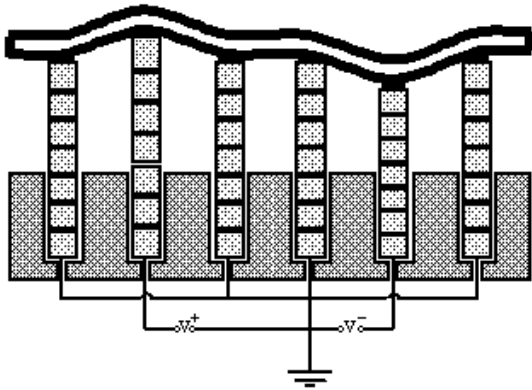


- Adaptive Optics:
 - Schematics



What is MCAO ?

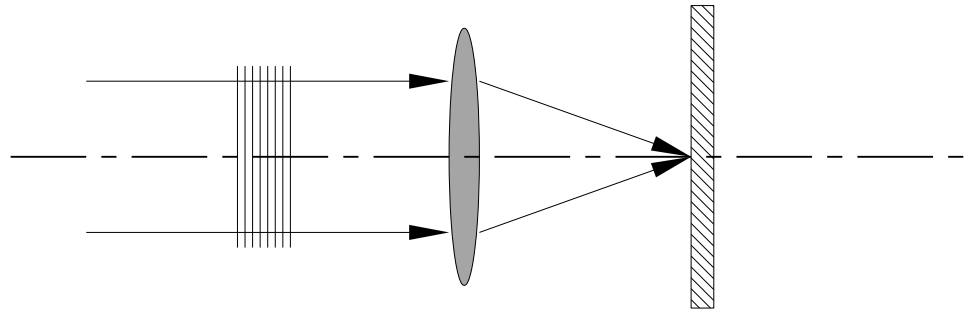
- Adaptive Optics:
 - Schematics
 - Deformable mirror:
 - from $\varnothing 10\text{mm}$ to $\varnothing 1\text{m}$
 - Flat or powered



What is MCAO ?



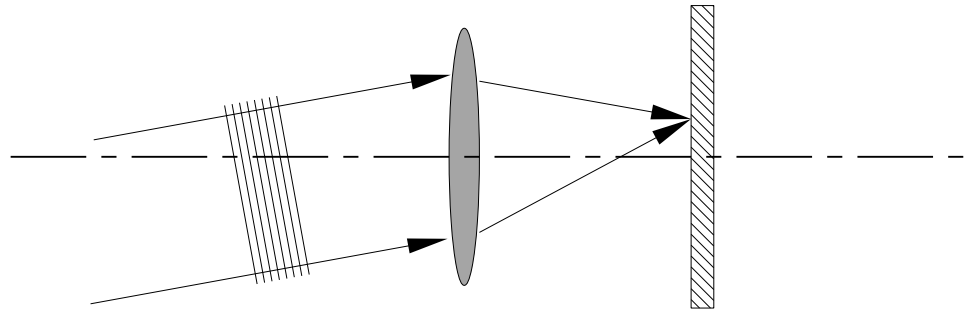
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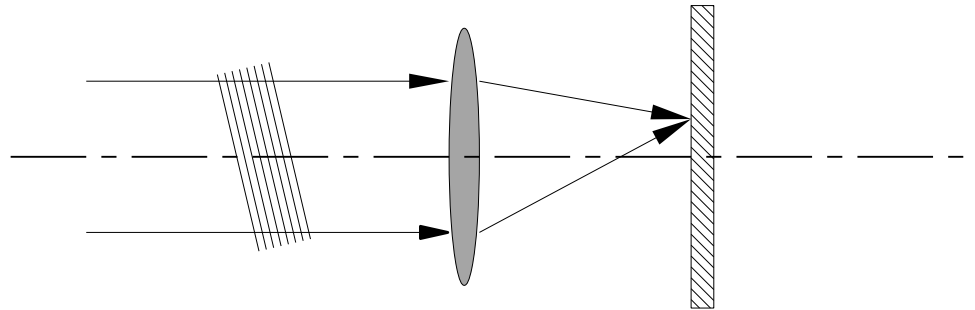
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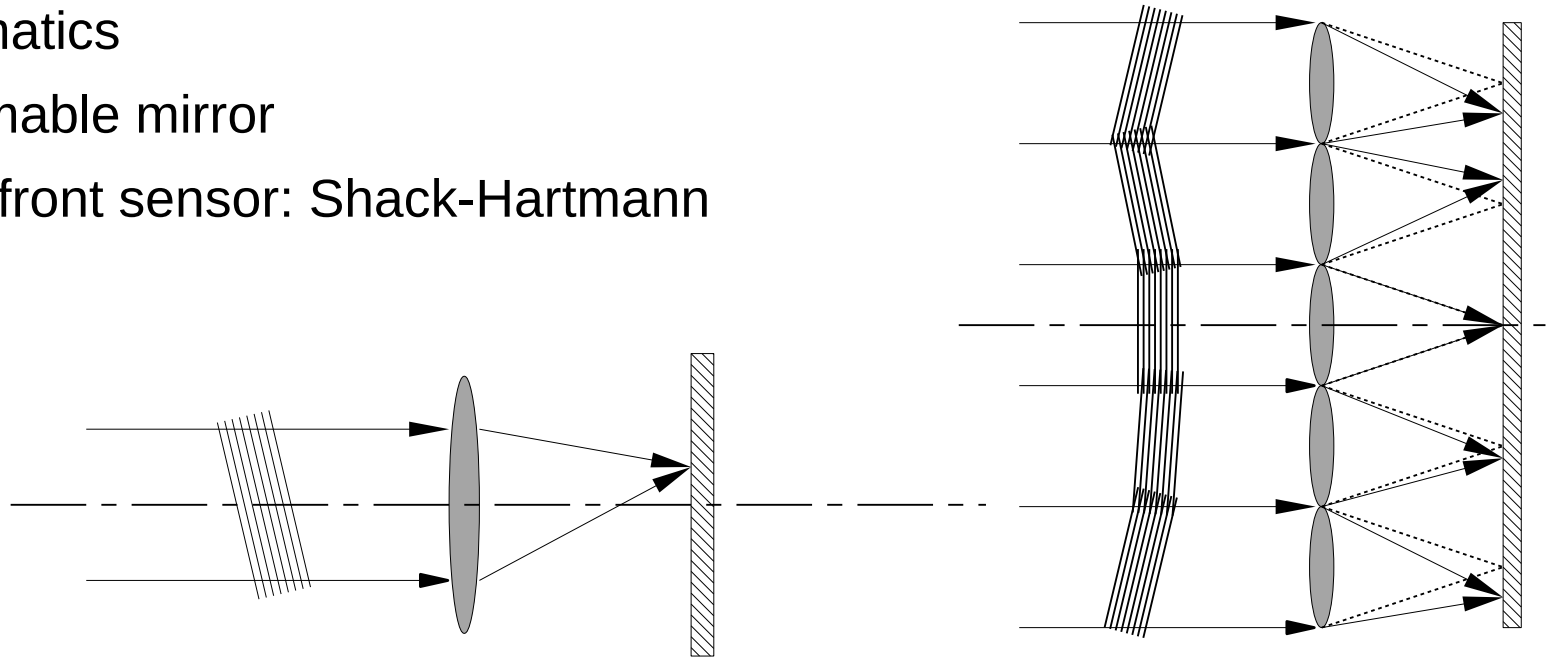


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- Adaptive Optics:

- Schematics
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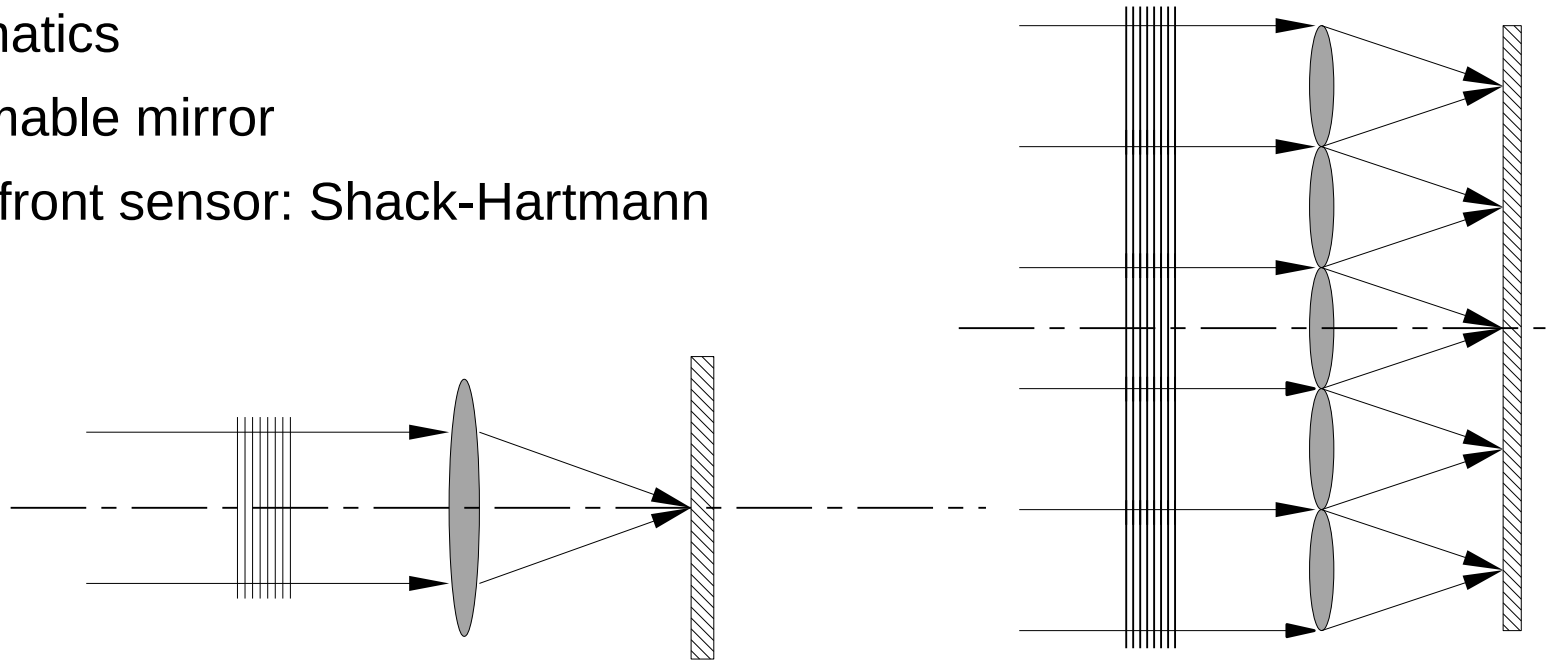


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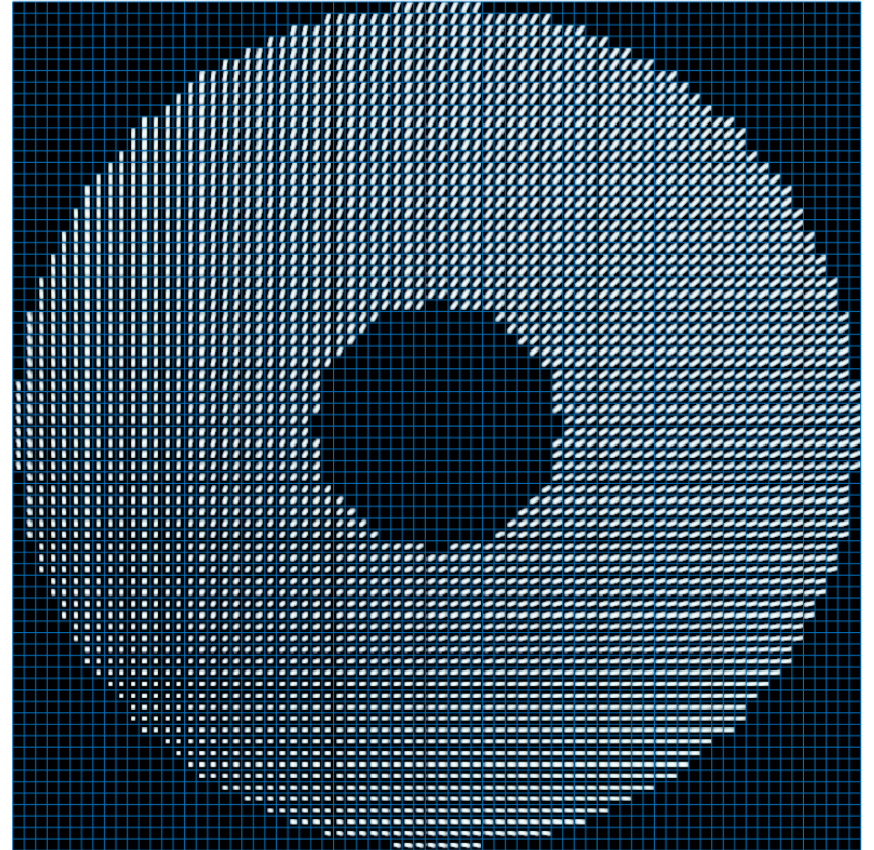
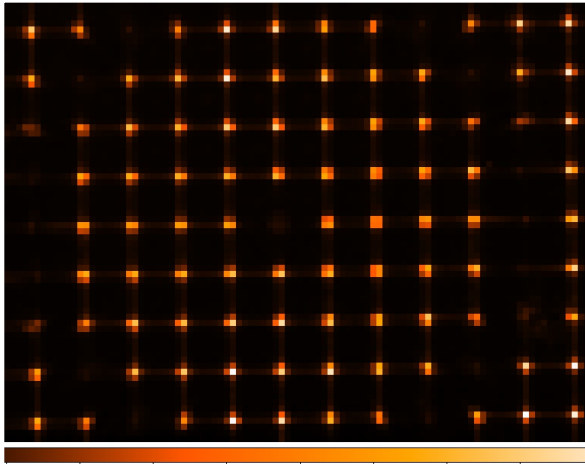
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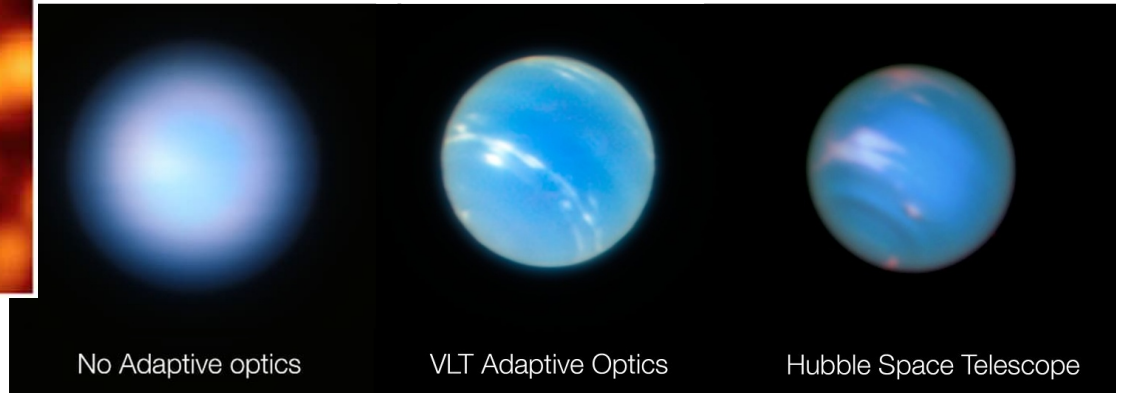
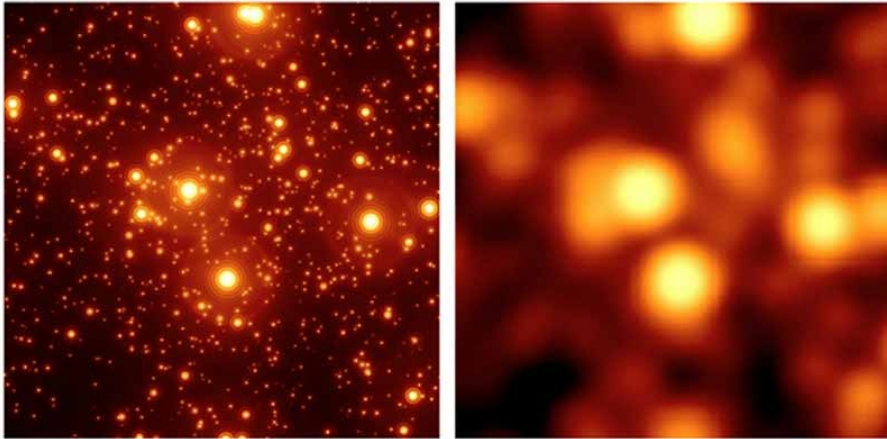
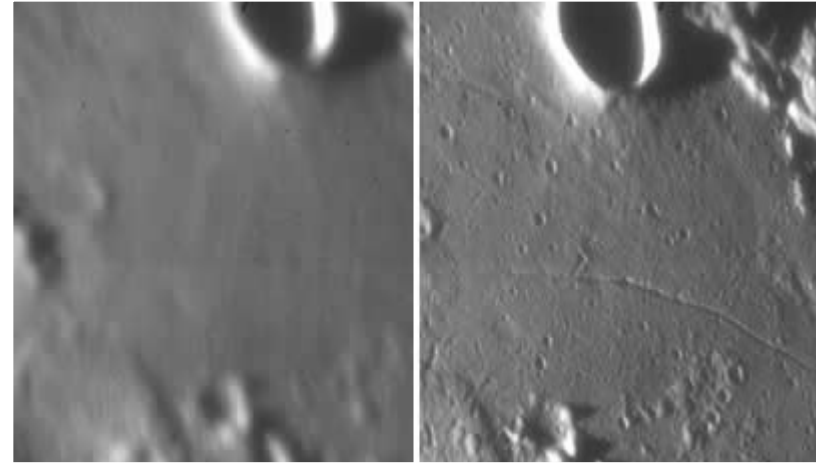
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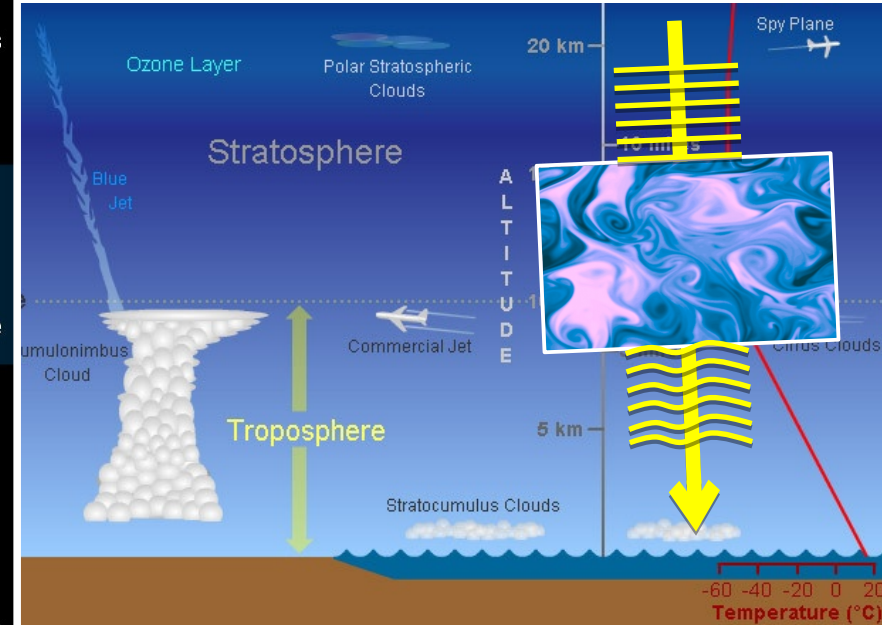
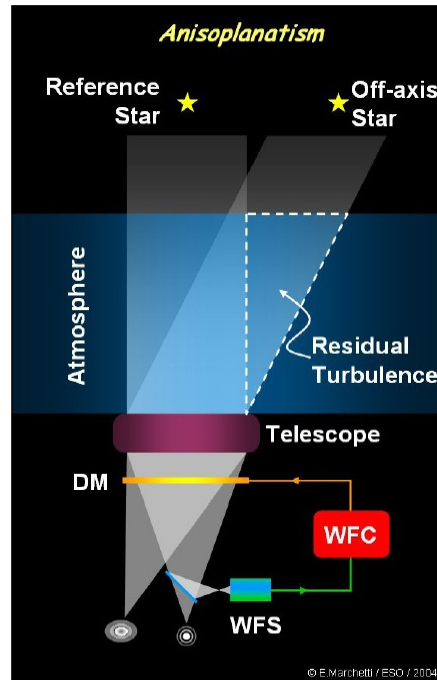
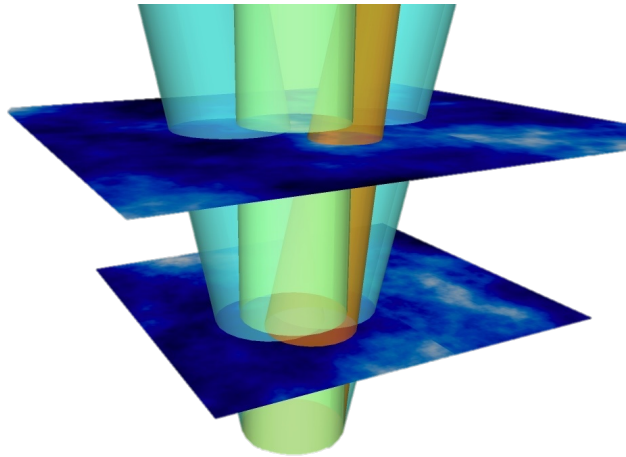
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 - Now a proven technique



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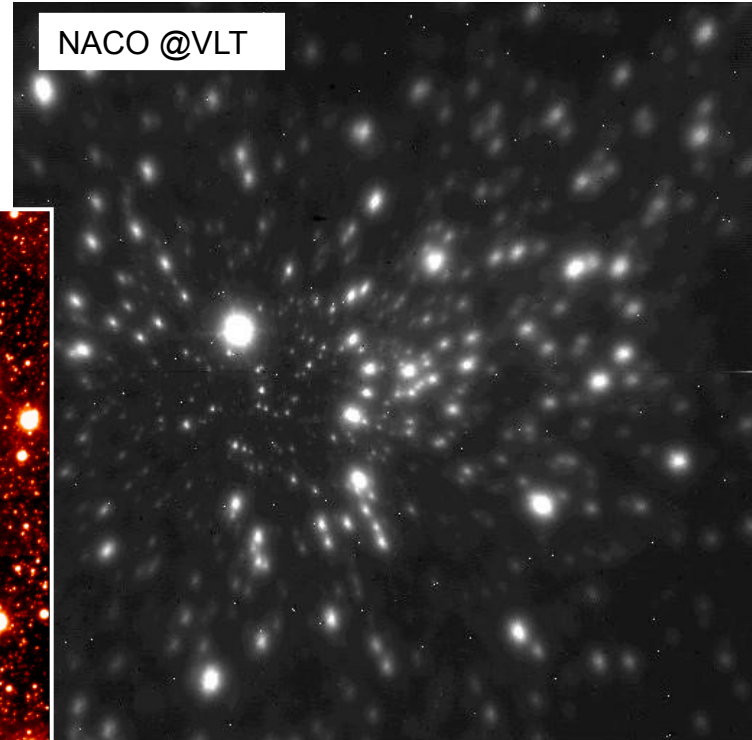
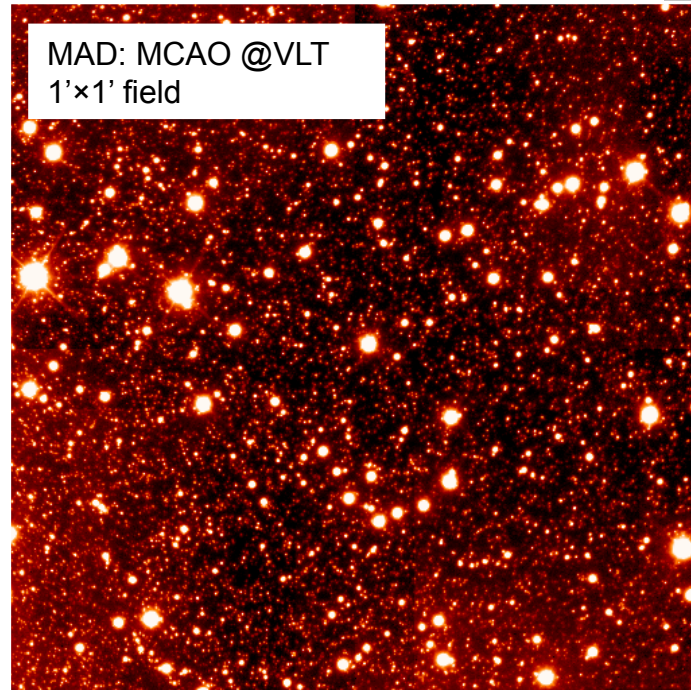
- Adaptive Optics:
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 - Why MCAO ?
 - Anisoplanatism



What is MCAO ?



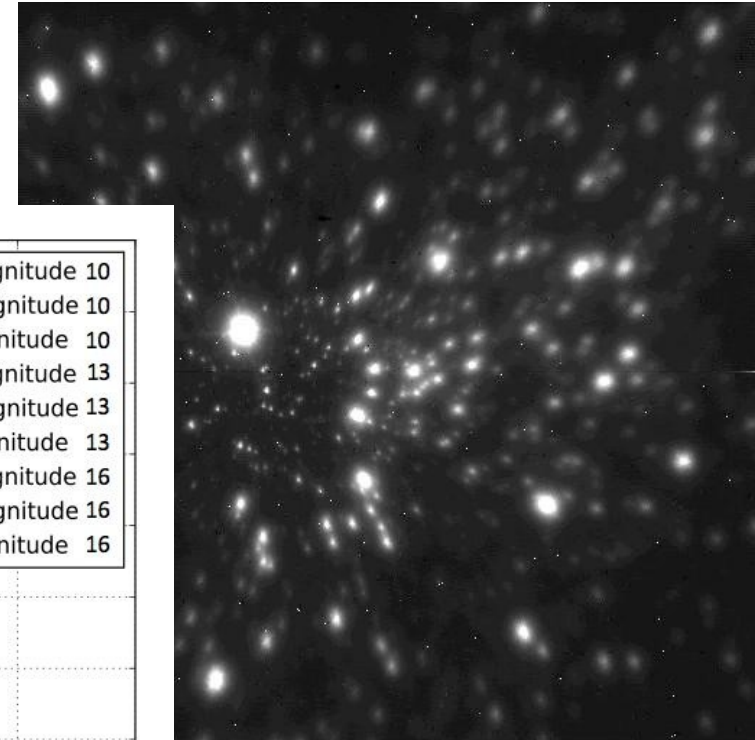
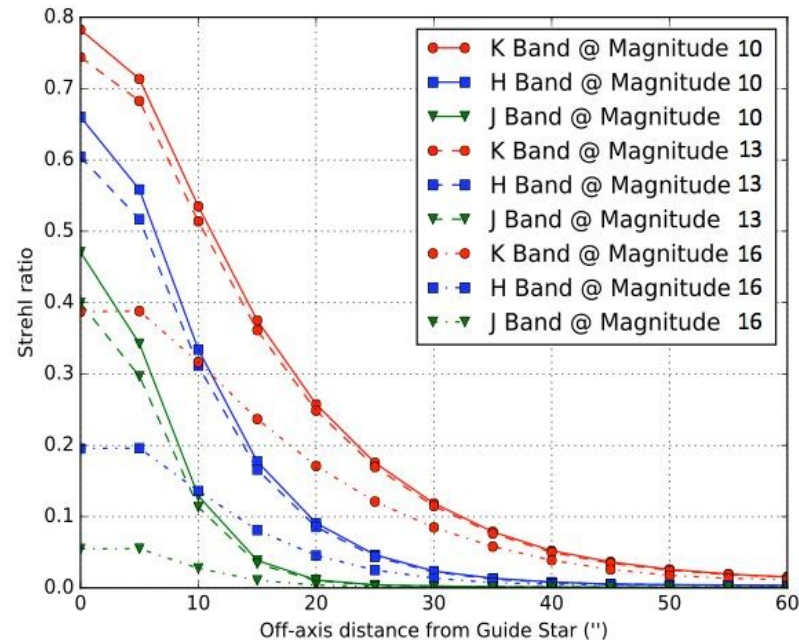
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MICADO-SCAO @ELT
1'x1' field

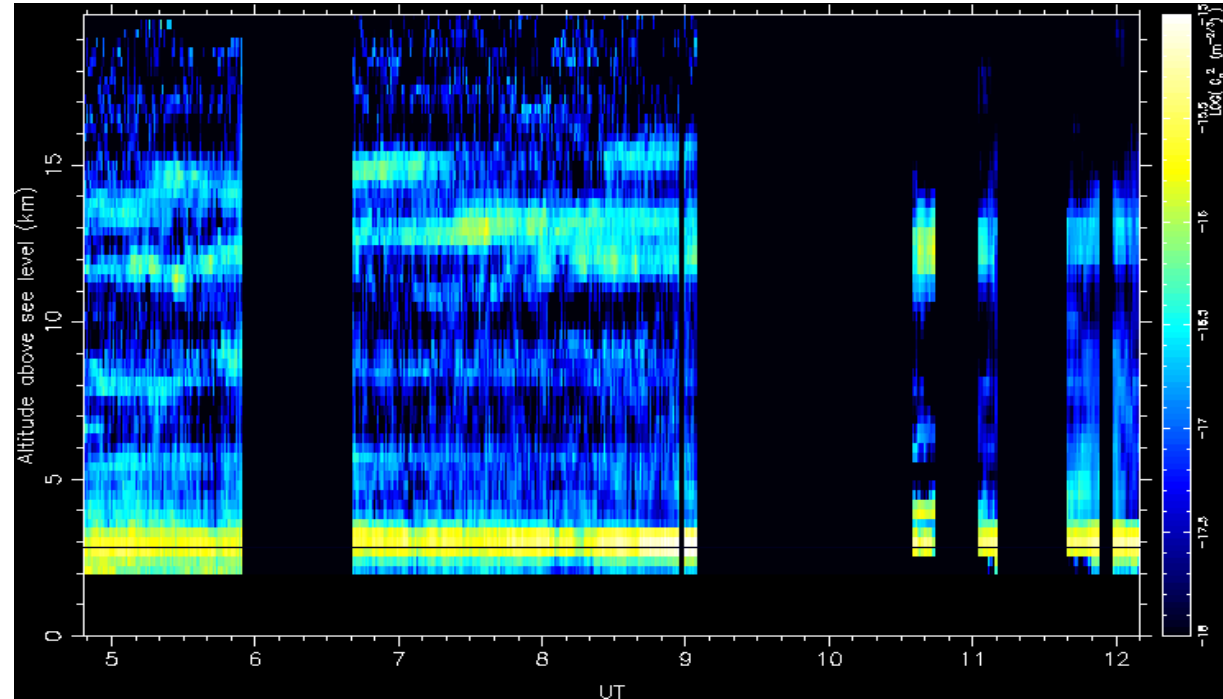


What is MCAO ?



- Adaptive Optics:

- Why MCAO ?
- Anisoplanatism
- Atmosphere turbulence is in layers

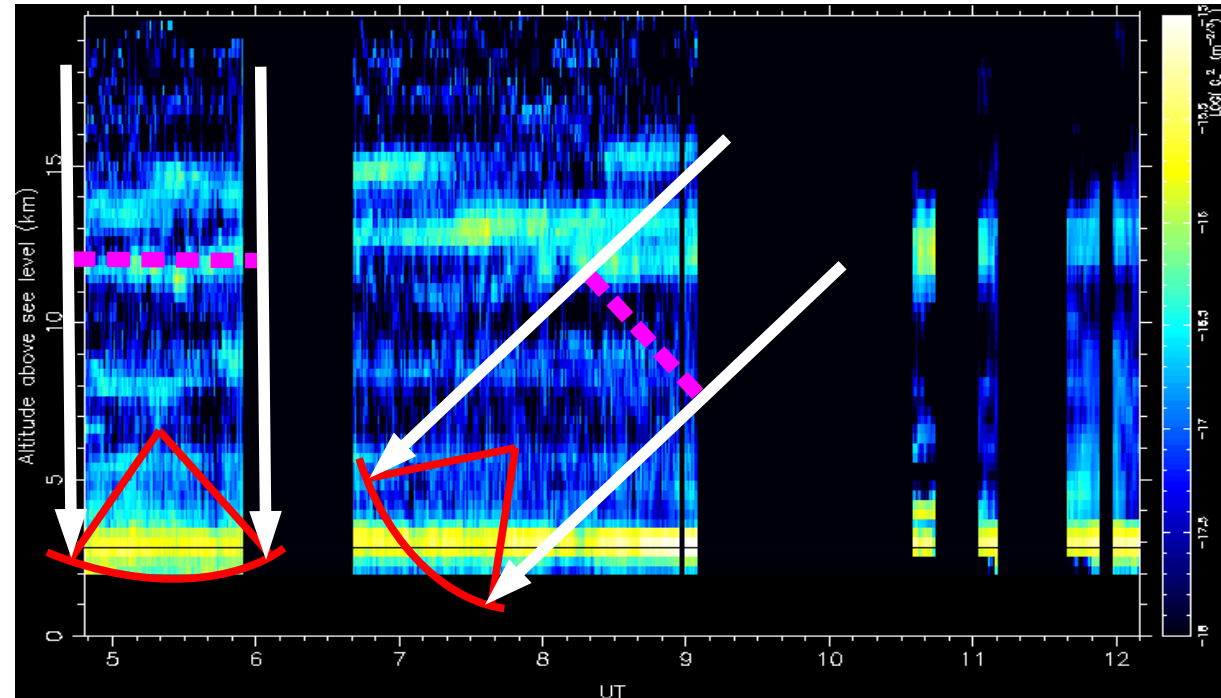


What is MCAO ?



- Adaptive Optics:

- Why MCAO ?
- Anisoplanatism
- Atmosphere turbulence is in layers
- MCAO : conjugate DM on those layers
 - correct conjugation is a statistical choice

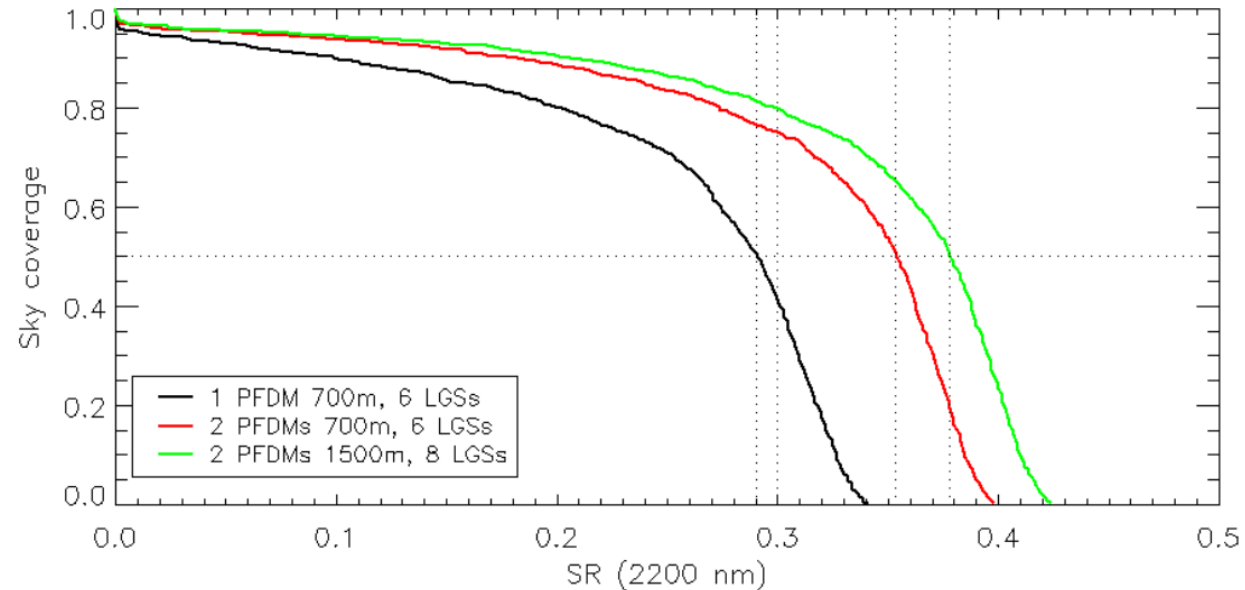
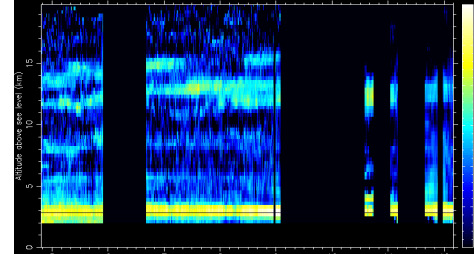


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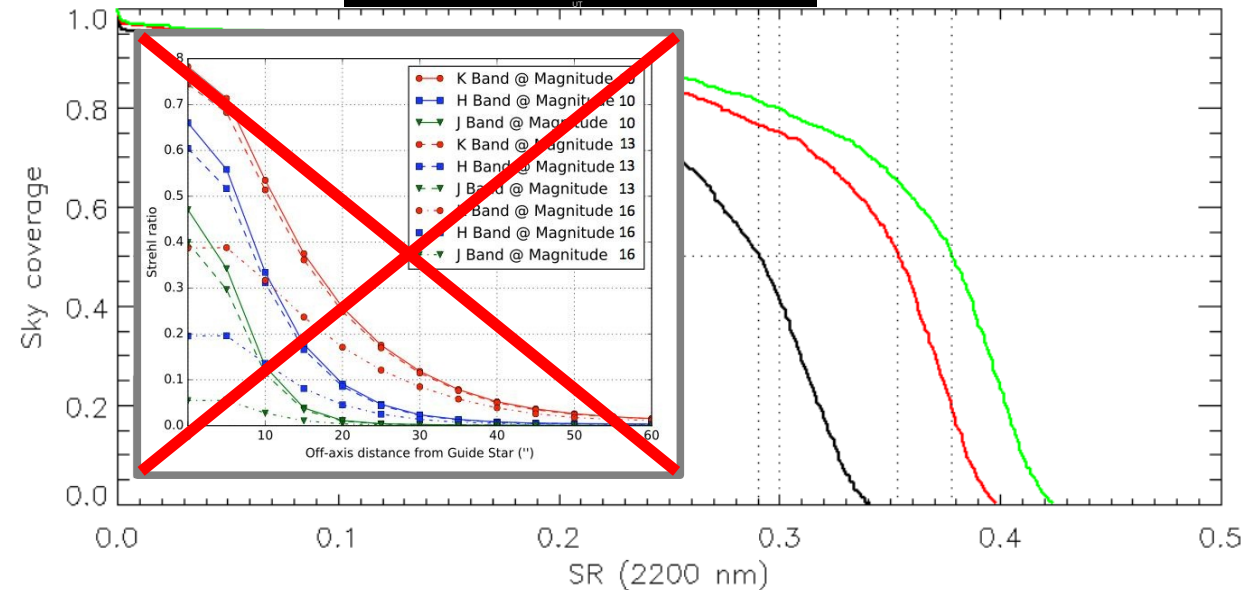
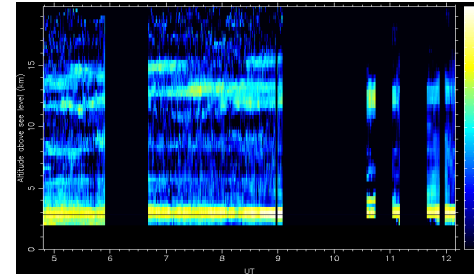
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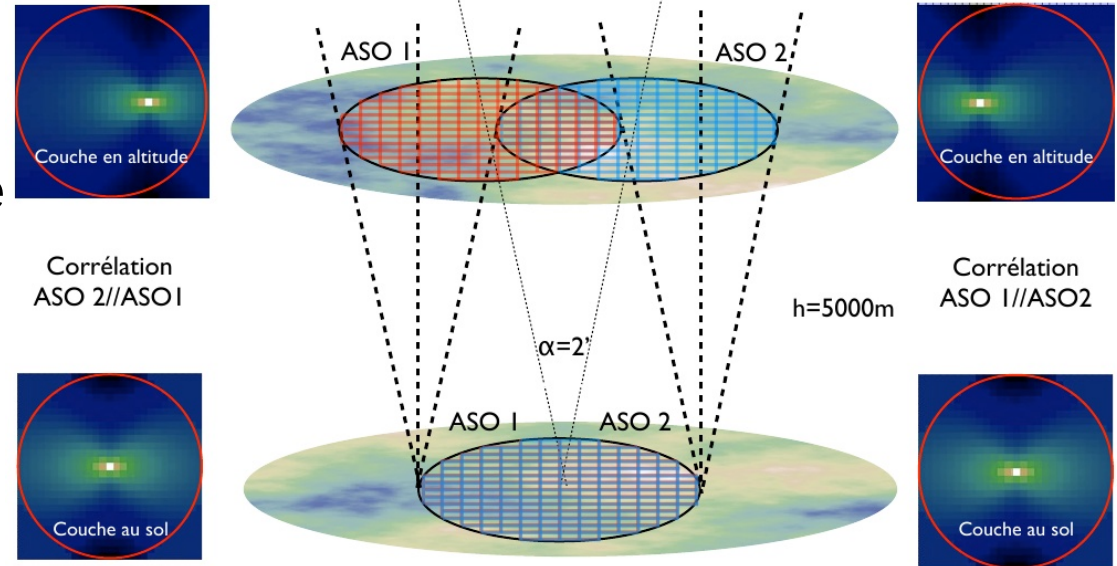


What is MCAO ?

- Adaptive Optics:

- Why MCAO ?
- Tomography :
How to reconstruct
the atmosphere in 3D ?
- Measure and fit covariance
matrices between WFS

Carte de covariance des pentes entre 2 ASOs

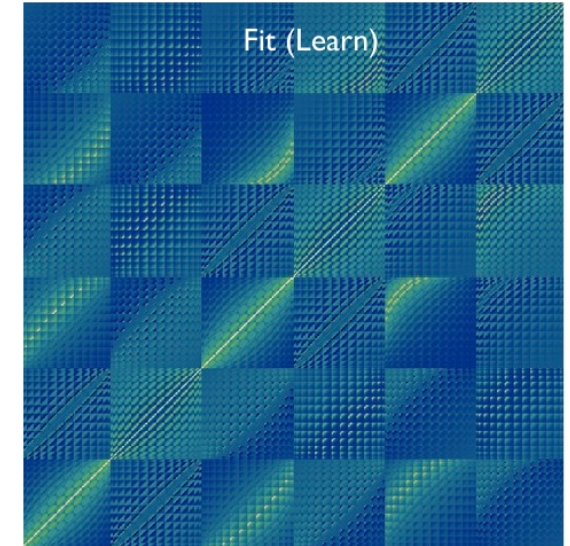
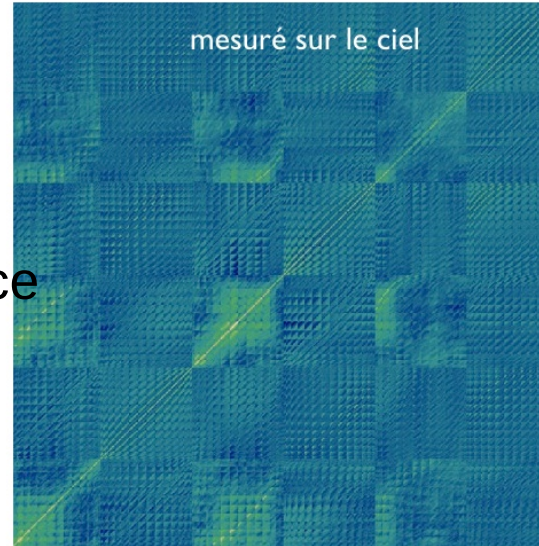


What is MCAO ?



- Adaptive Optics:

- Why MCAO ?
- Tomography :
How to reconstruct
the atmosphere in 3D ?
- Measure and fit covariance
matrices between WFS
- Learn&Apply
(CANARY 2010)

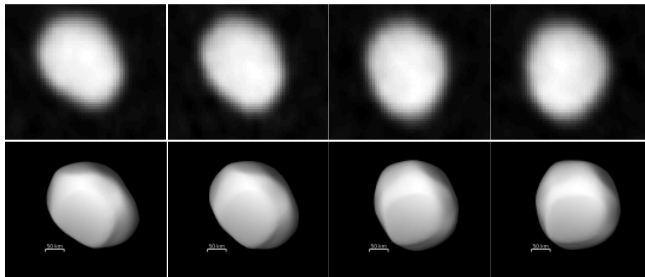


What is MCAO ?



- Adaptive Optics: MAORY configuration
 - 6 LGS (may-be 8)
 - $\varnothing 1.5$ arcmin (0.45" radius)
 - 3×2 NGS WFS (LOR)
 - 3 modules on X-Y stages patrolling $\varnothing 3$ arcmin field
 - Low-Order fast IR WFS: 2×2 subaps @SAPHIRA ?
 - Reference WFS: 10×10 subaps @CCD220 camera
 - 2 DM:
 - Conjugated @6km & 15km
 - ~700 modes (actuators) ~30×30

- Adaptive Optics: MAORY science case
 - Solar system

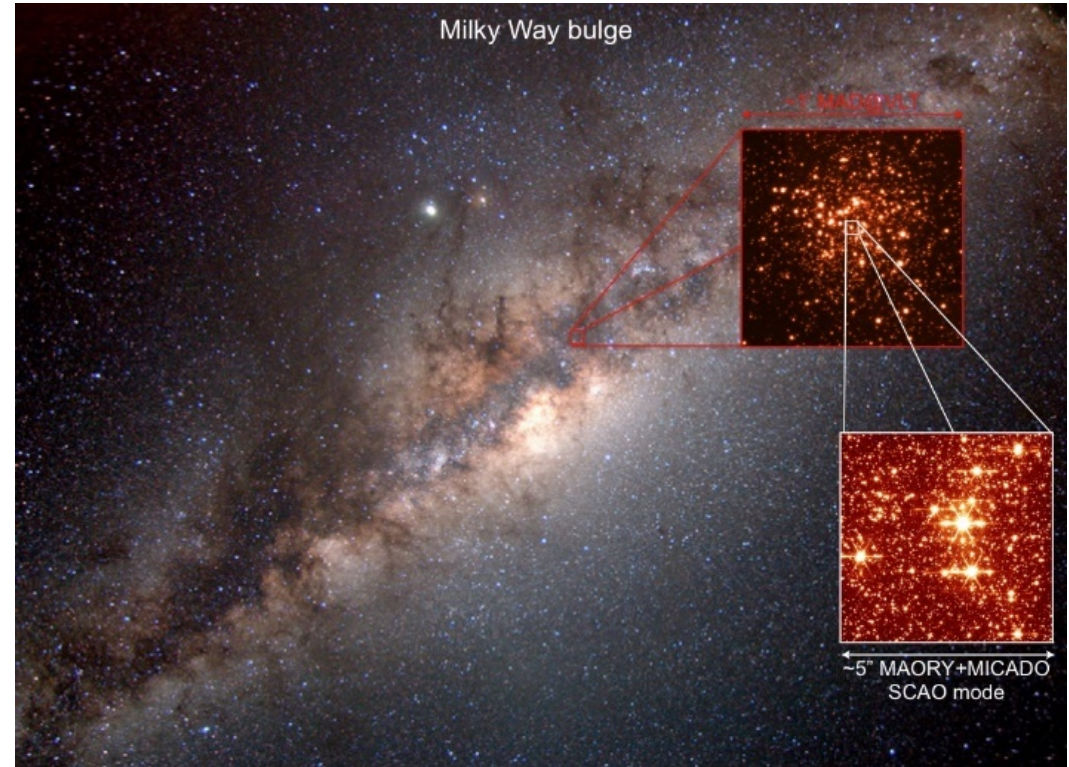


Juno by par SPHERE@VLT

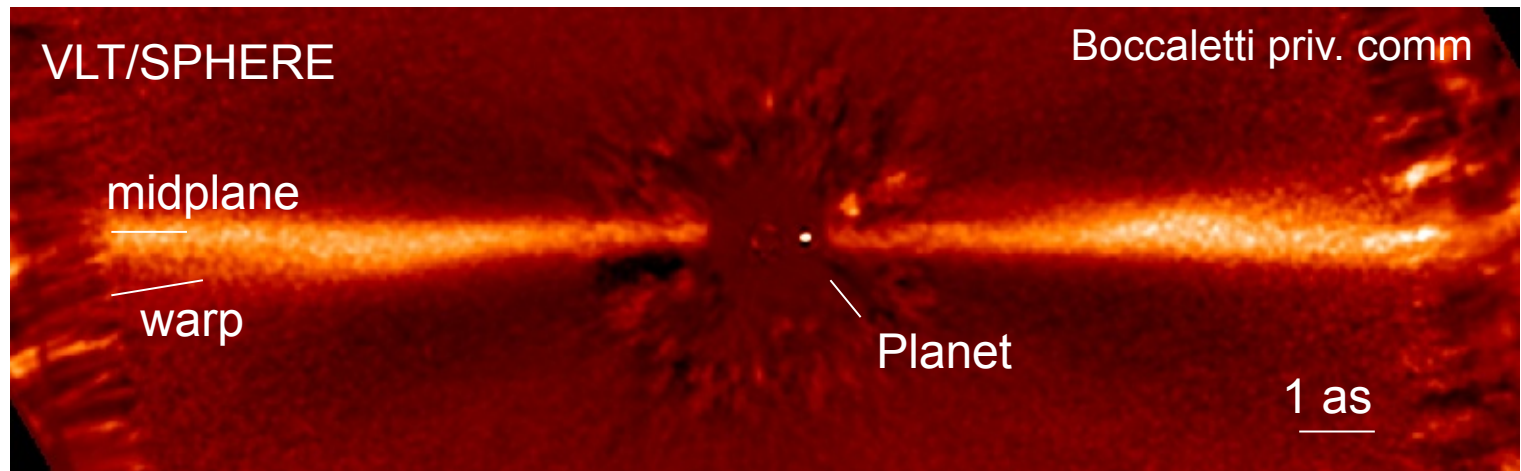


Figure 8: J, H and K' color composite of Uranus (left), H and K' color composite of Neptune (middle) and K' image of Titan (right). The inset on the top left is an enlarged image of Miranda at K'.

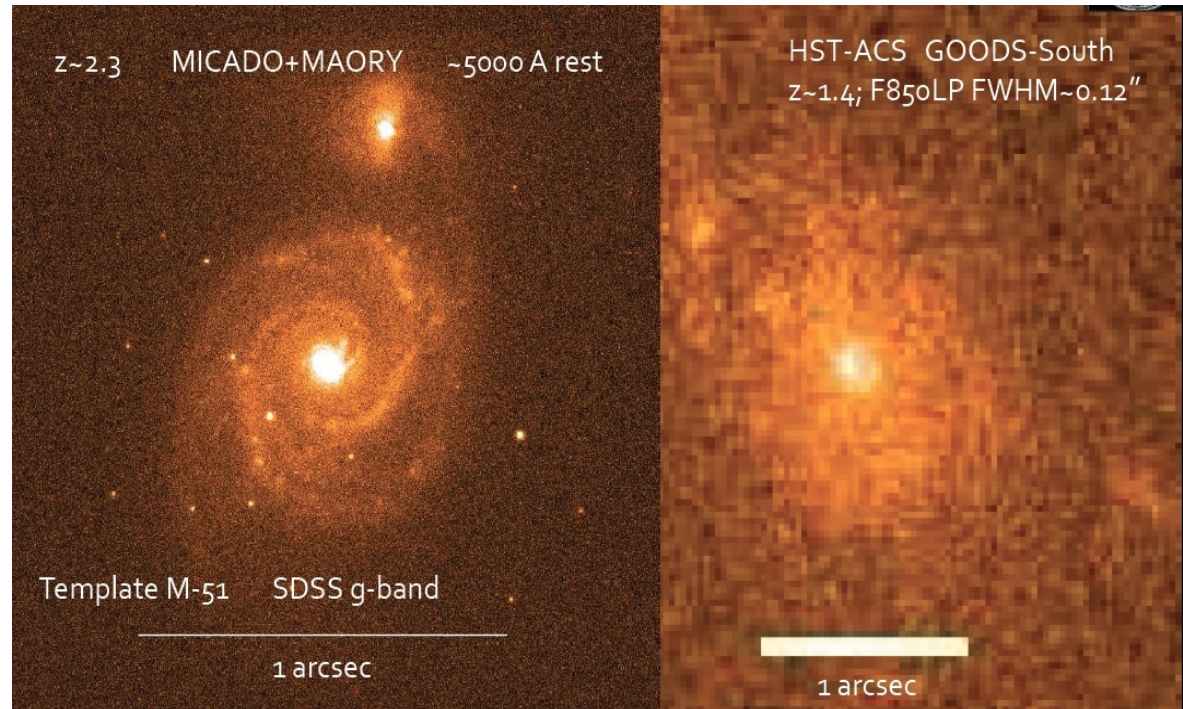
- Adaptive Optics: MAORY science case
 - Star formation and evolution in nearby stellar systems
 - MCAO: justified by the PSF uniformity and the astrometric precision over a large FOV (50") that will increase stellar statistics.



- Adaptive Optics: MAORY science case
 - Disks and Exoplanets
 - Pure SCAO science case with angular differential imaging & coronagraphy



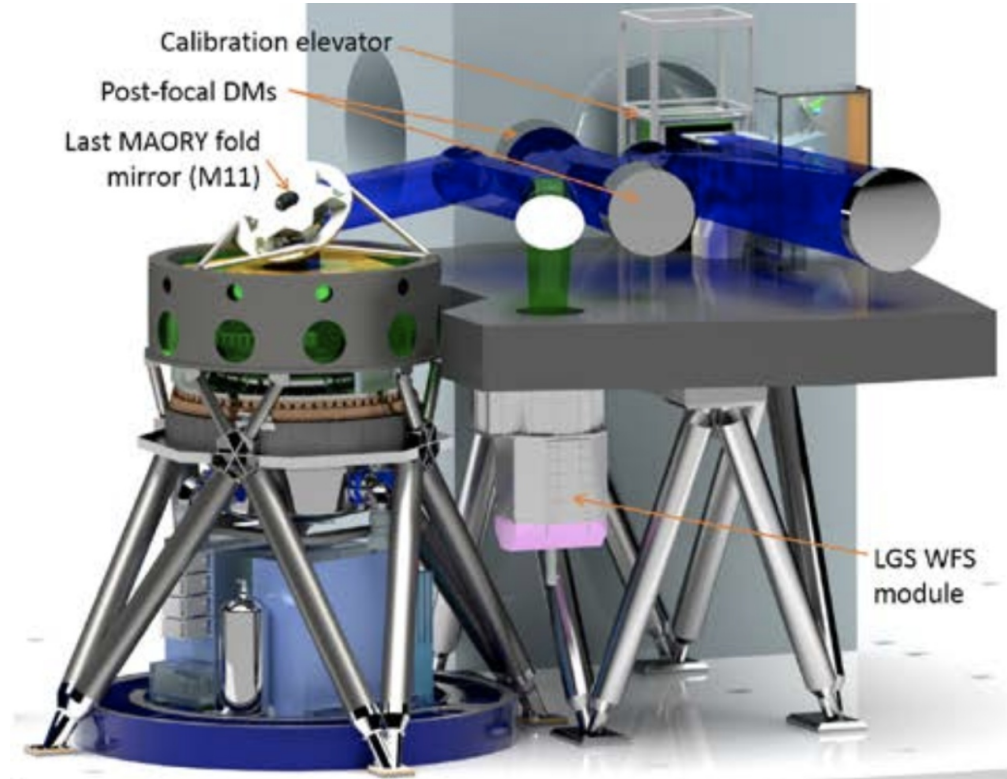
- Adaptive Optics: MAORY science case
 - High redshift universe
 - MCAO is preferred for AO sky coverage issue, PSF uniformity over large field, and target magnitude constraint.



MAORY Optical Design History

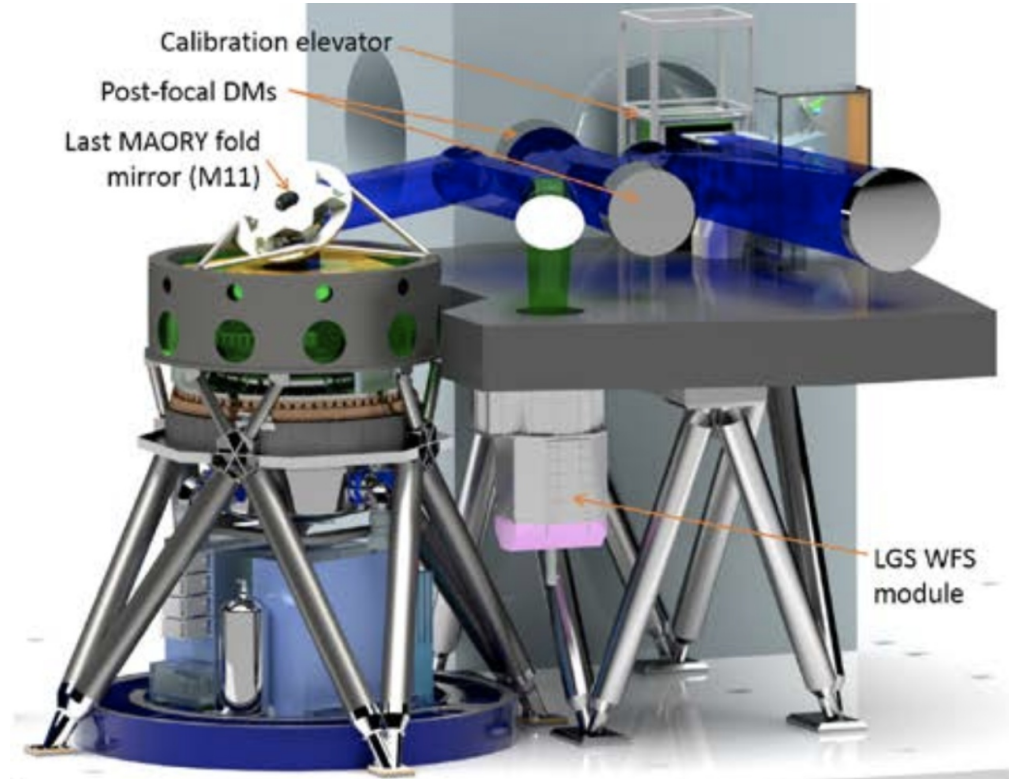


- MICADO: what is it ?
 - General purpose imager for ELT (~CONICA was for VLT)
 - 1'×1' field of view, zoom mode 20"×20", spectrographic and coronagraphic modes
 - 9 (3×3) Hawaii4 RG (12000×12000 = 144 Mpixels !!!)
 - Cryostat Ø2.5m, on Nasmyth platform, rotation gravity invariant



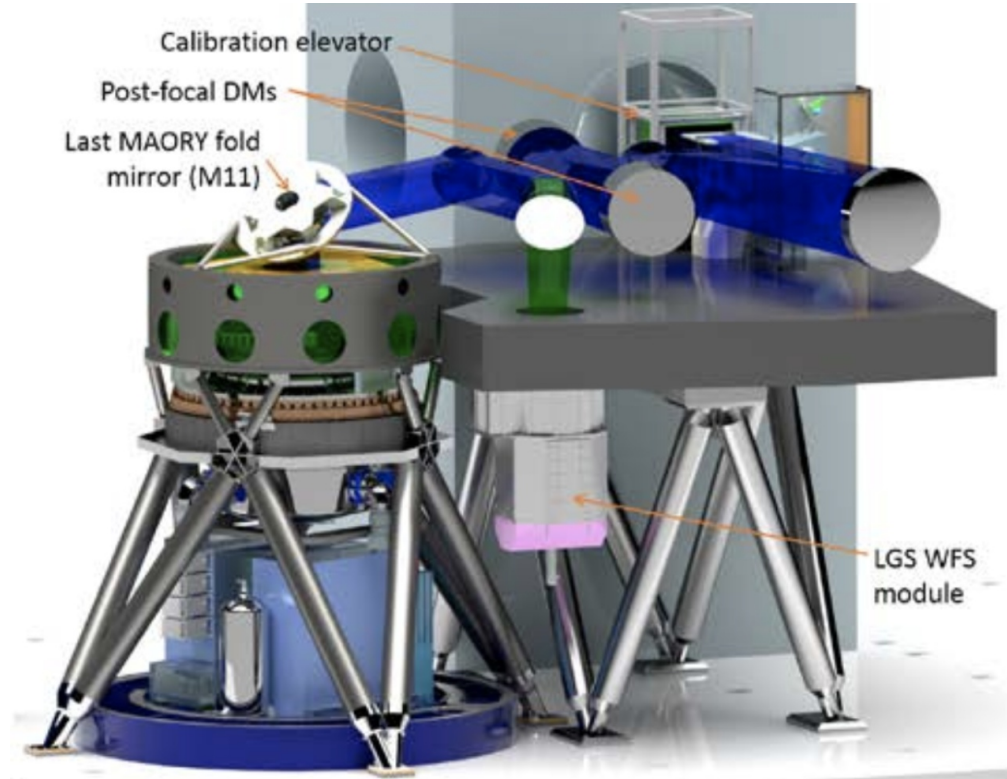
- MICADO history:

- Contract signed: 18 sept 2015
- Instrument kick-off: 6 oct 2015
- PDR: november 2018
- FDR: end 2020 (TBC)
- PAE: 2024
- PAC SCAO: 2025
- PAC MCAO: 2027

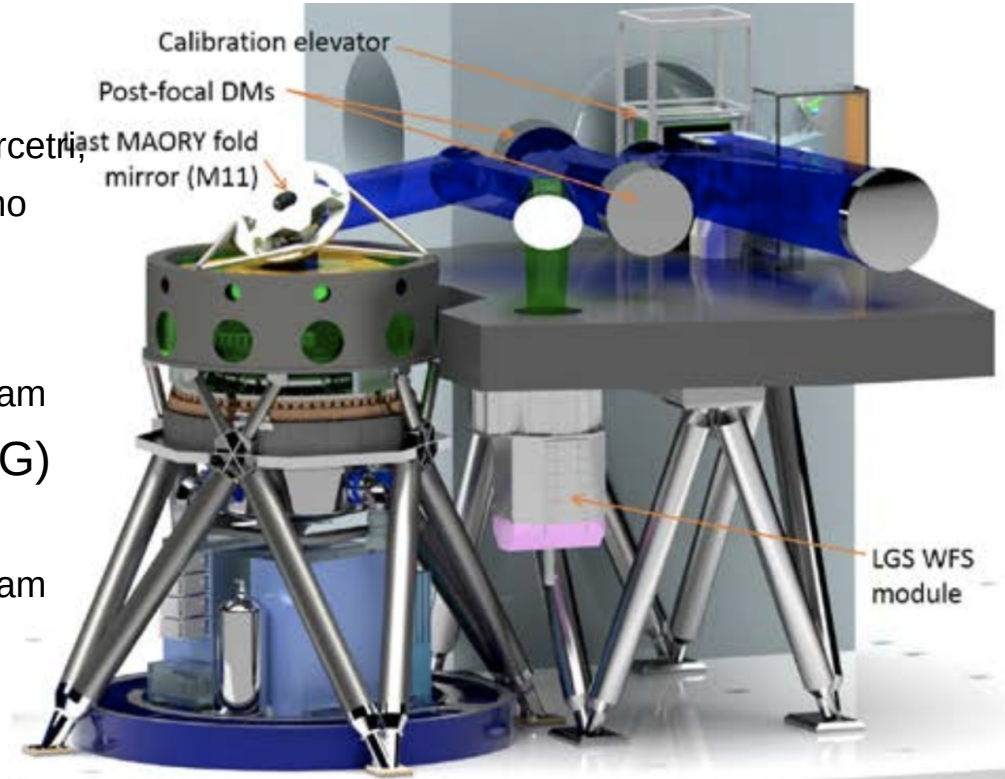


- MICADO → MAORY specifications

- defined in #ESO-254311
- Field of View :
 - MICADO science : $\varnothing 70$ arcsec
 - MAORY technical FoV: $\varnothing 3$ arcmin
 - 2nd port : $> \varnothing 2.5$ arcmin
- Magnification : 1:1
- Throughput : $> 65\%$
- 2 DMs
- AO: 50% Strehl $\lambda = 2.2 \mu\text{m}$
@50% sky-coverage
- Astrometry



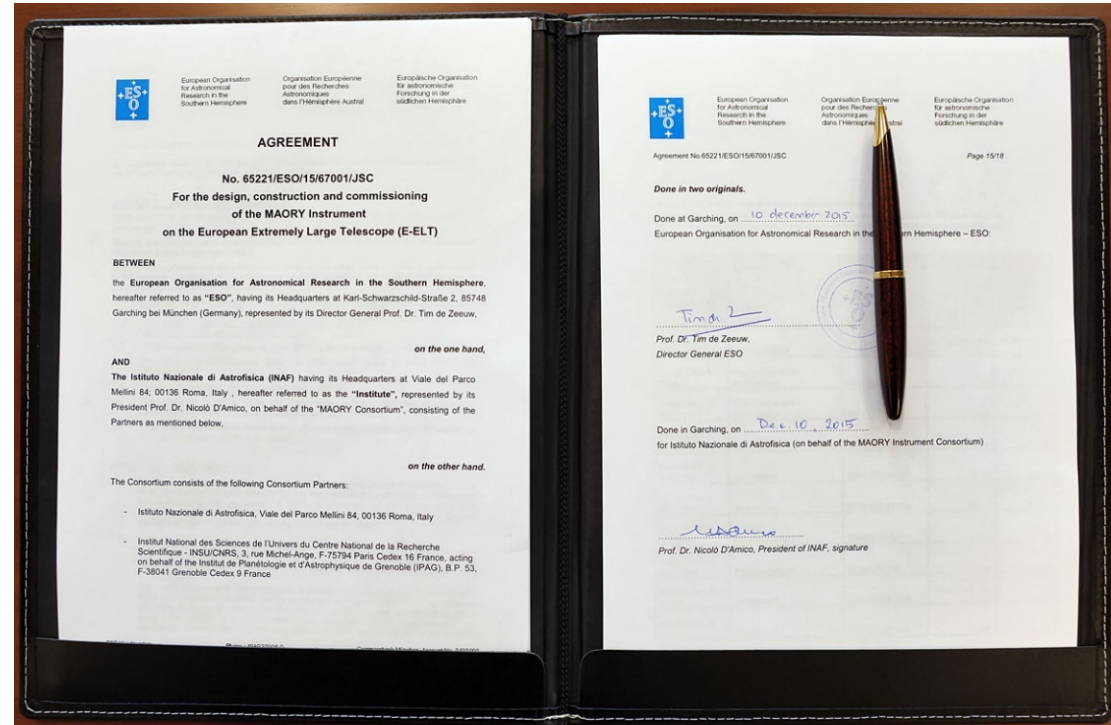
- INAF (Italy)
 - Acting as Lead institute
 - System level of MAORY
 - 6 INAF Institutes are involved: OAS Bologna, OA Arcetri, OA Brera, OA Capodimonte, OA Padova, OA Teramo
- INSU IPAG (France)
 - LGS wavefront sensor
 - Contribution to SAT, System Team and Science Team
- National University of Ireland Galway (NUIG)
 - Test and Wavefront Correction Verification
 - Contribution to SAT, System Team and Science Team
- ESO
 - Project customer
 - Supplier of components and services



MAORY Instrument History



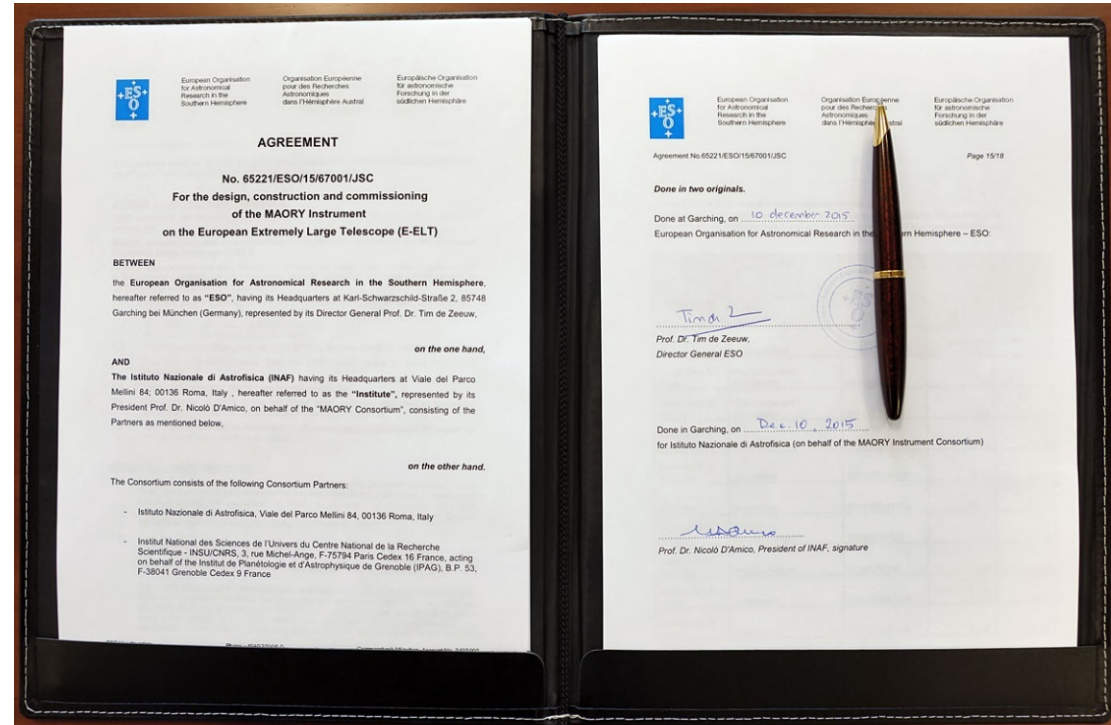
- Phase A
 - Nov 2007 - Dec 2009
 - Review held on December 10-11, 2009
- Phase B preparation
 - 2010 - 2015
 - Instrument re-baselining
 - Requirements definition
 - Contractual documents preparation
 - Consolidation of facilities at INAF
 - Consolidation of Consortium following ESO guidelines
- Agreement signature
 - 10 Dec 2015



MAORY Instrument History



- Conclusion of trade-off study
 - 14 Feb. 2020
- Phase B (PDR)
 - Feb. 2016 – Feb. 2021
- Phase C (FDR)
 - Feb. 2021 – Dec. 2022
- Phase D (MAIT)
 - Jul. 2021 – Mar. 2028
- PAE
 - Nov. 2027
- Phase E (Commissioning)
 - Mar. 2028 – Mar. 2029





Assessment - Summary

- Criterion 1: A feasible baseline instrument design compliant with the technical specifications and the interfaces to the ELT, MICADO and a 2nd port instrument partially compliant
 - good technical progress, AO design solid,
 - trade-off inconclusive and incomplete; maturity of MOC design insufficient
 - Non-compliances: mass, volume, 2nd port, only 6 LGS
- Criterion 2: A credible schedule for the design, development, construction, installation and commissioning of the MAORY instrument within the available budget partially compliant
 - PDR schedule (Apr 2020) not credible >> NET end 2020
 - Cost information limited >> but little difference between the options
 - Full cost estimate only at PDR



MAORY Optical Design History

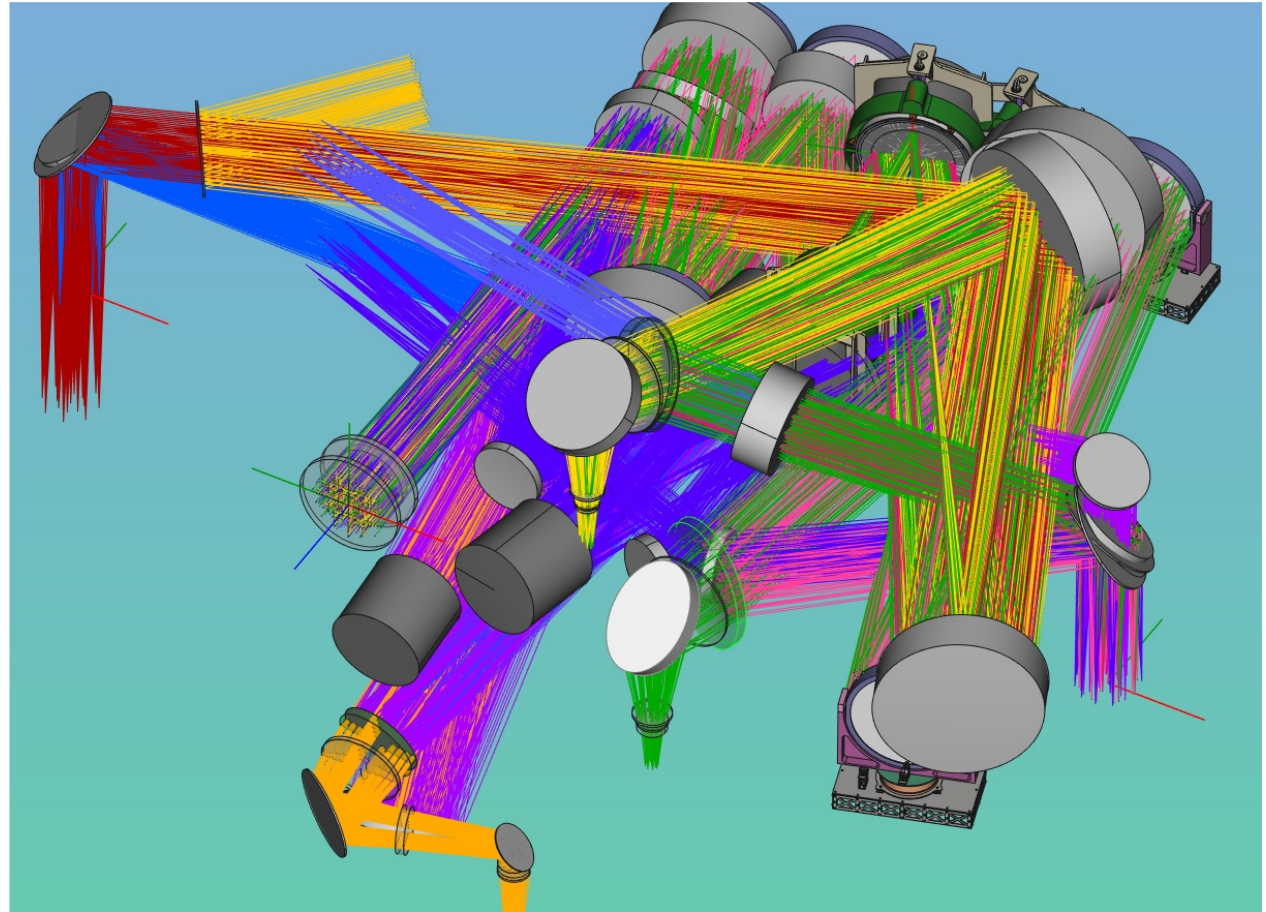


- **AMC** : *Original design up to November 2018*
- **MOC** : *Design presented to ESO in July 2019*
- **miniMOC** : *Design evolution for weight-gain, october 2019, compatible with 2nd port if LGS-WFS duplicated*
- **MMS** : *Initial design proposed by ESO in september 2019, adapted and modified by MAORY team, proposed as base-line in january 2020, confirmation pending (february 2020 ?)*

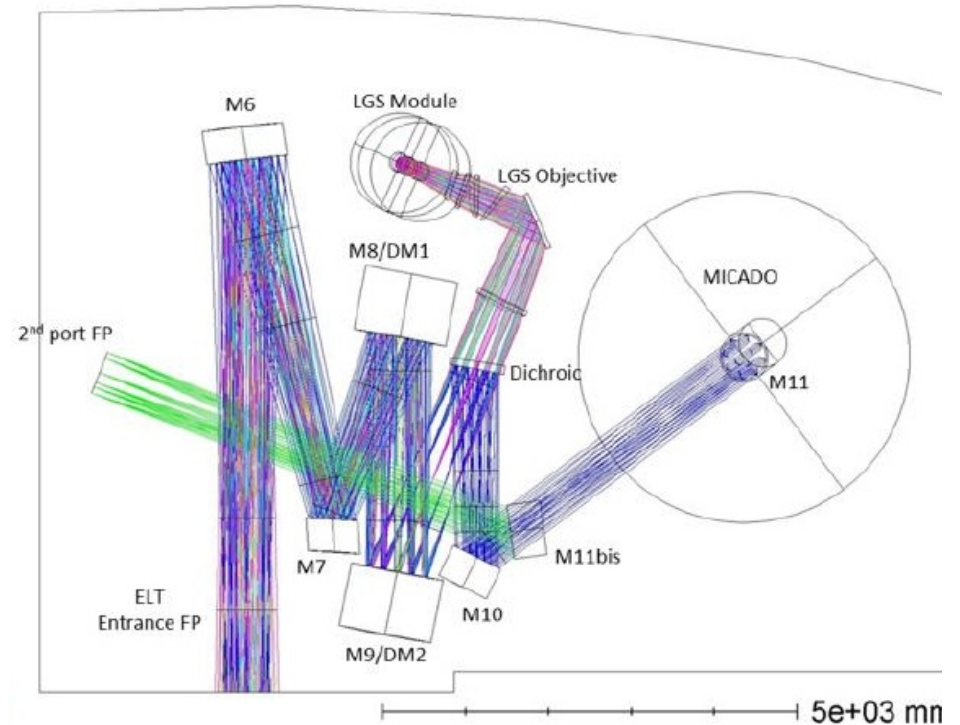
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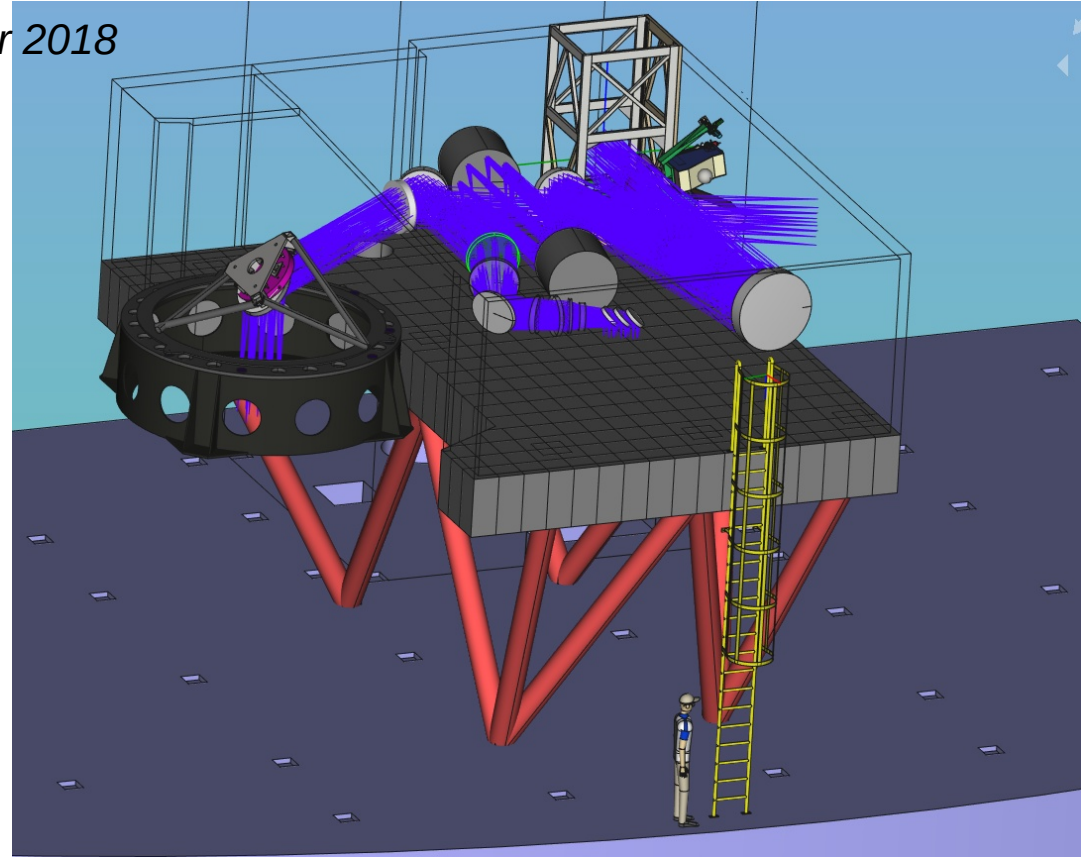
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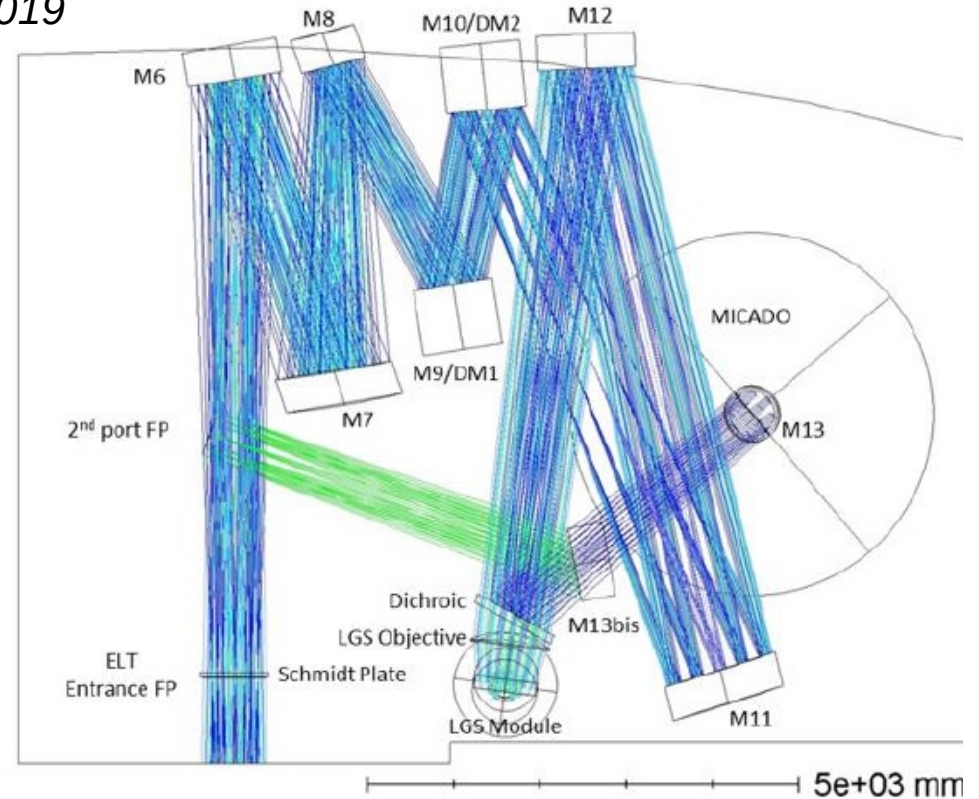
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- **Aspheric Mirror Concept**
 - 5 aspheric surfaces
 - Difficult to manufacture
 - Difficult to align
 - Compact
 - Flat focal plane
 - Incompatible with latest 2nd port requirements



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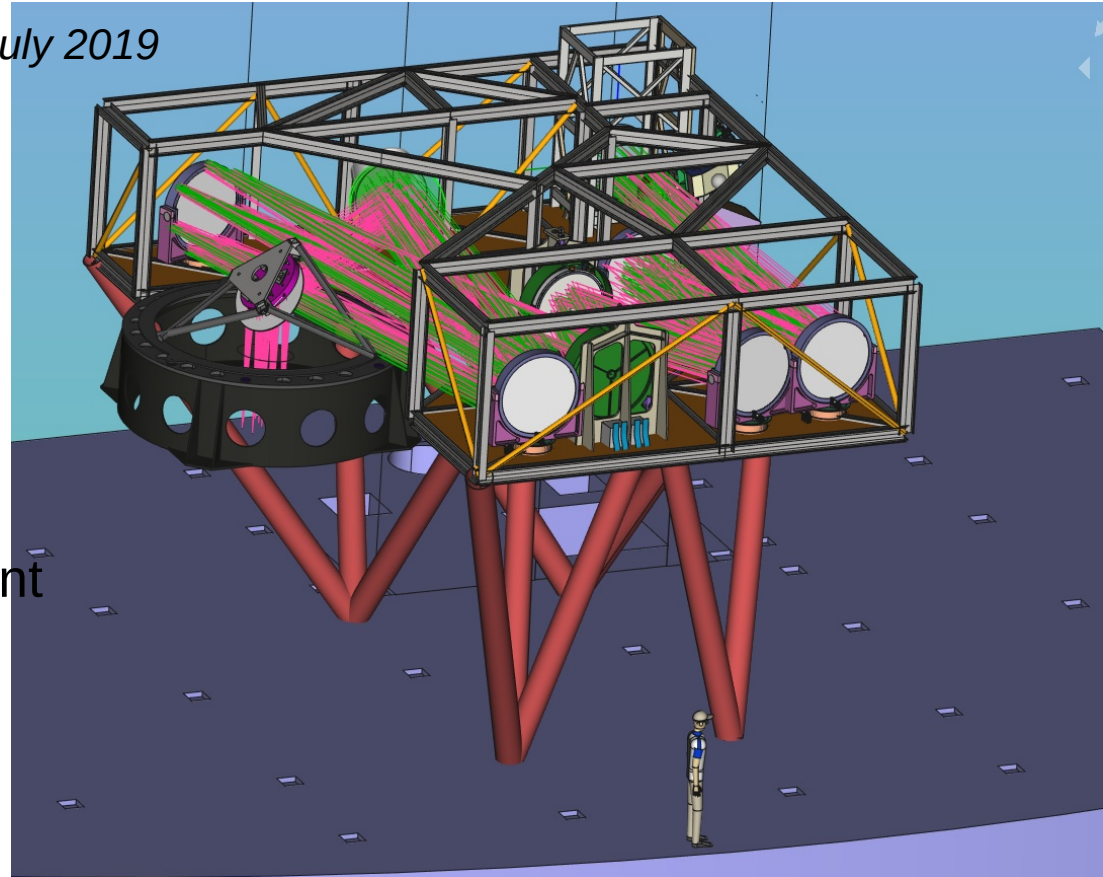
- MOC : *Design presented to ESO in July 2019*
- Modified Offner Concept
 - Schmidt-plate
 - 2 flat Dms
 - Curved focal plane ($R \approx 10\text{m}$)
 - Big & Heavy
 - Easy manufacture & alignment



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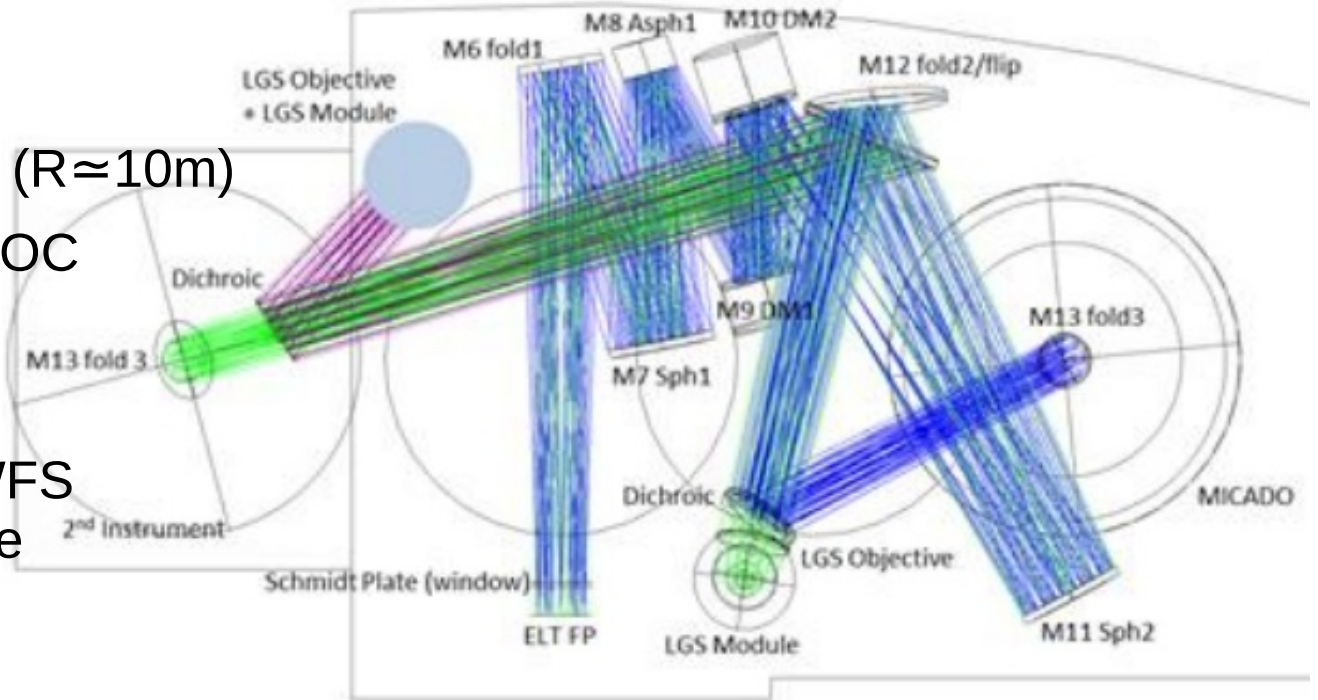


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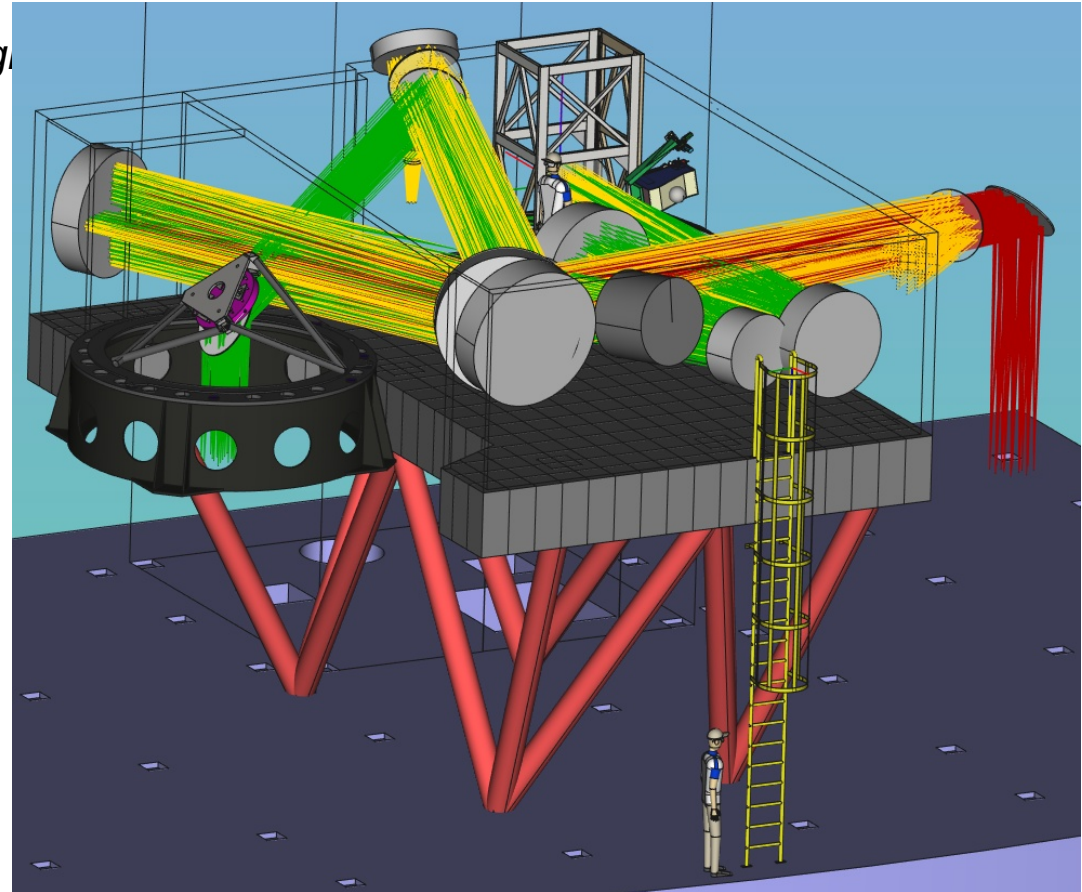


- **miniMOC** : *Design evolution for weight-gain, september 2019*

- Schmidt-plate
- 2 flat Dms
- Curved focal plane ($R \approx 10\text{m}$)
- Smaller than the MOC
- Easy manufacture & alignment
- Duplicating LGS-WFS makes it compatible with latest 2nd port requirements



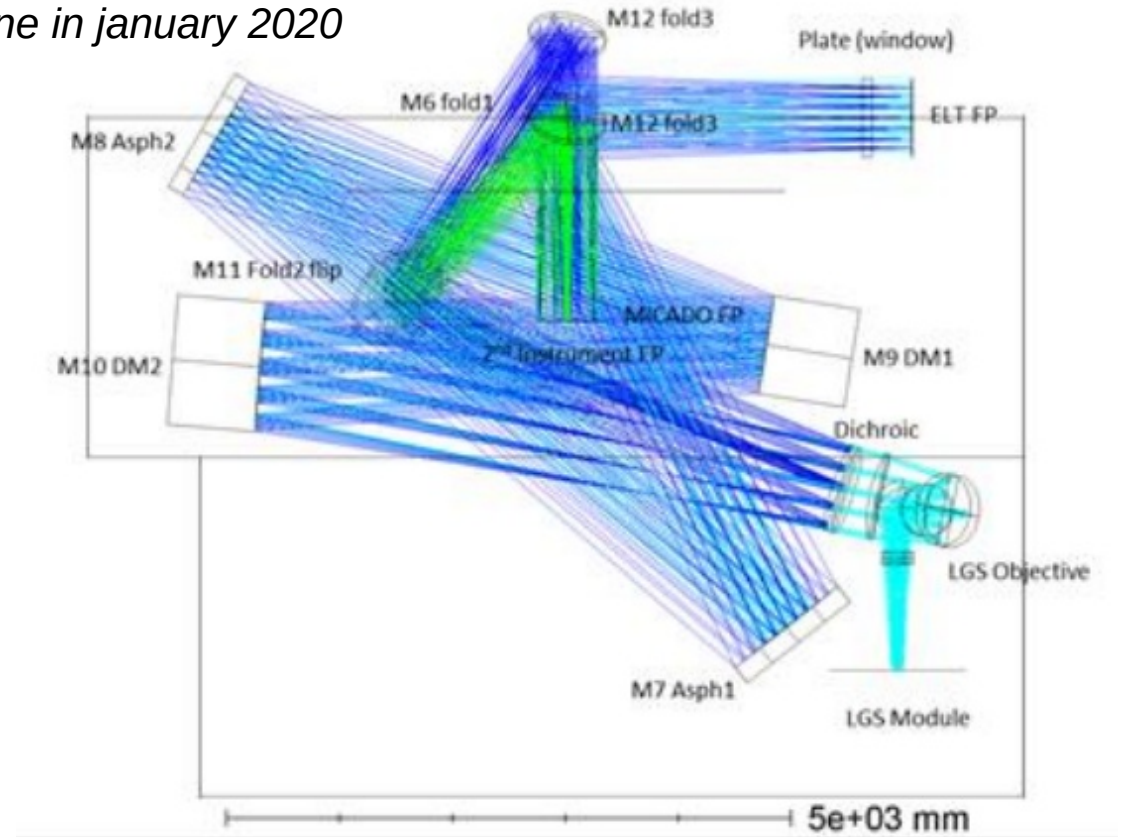
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MAORY Optical Design History



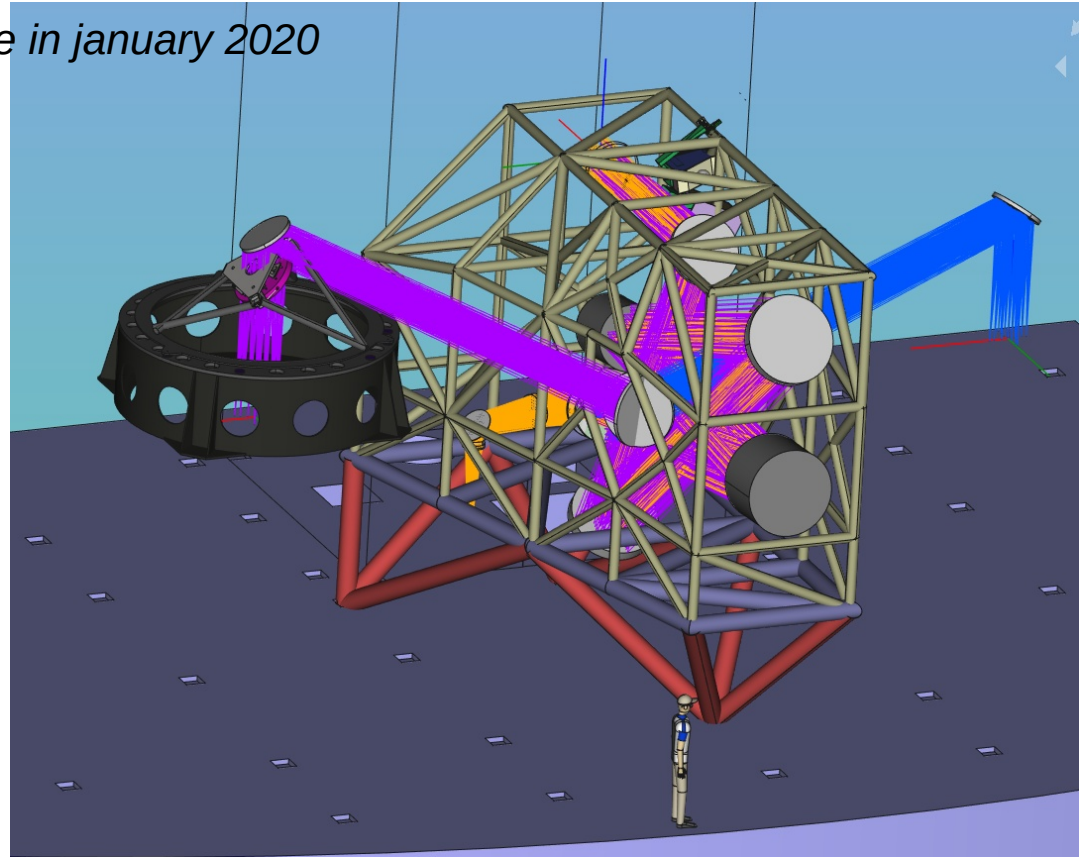
- **MMS** : *Design proposed as base-line in january 2020*
 - Schmidt plate
 - Vertical plane
 - Curved Dms
 - Flat output focal plane
 - 3D laser tracker alignment



MAORY Optical Design History



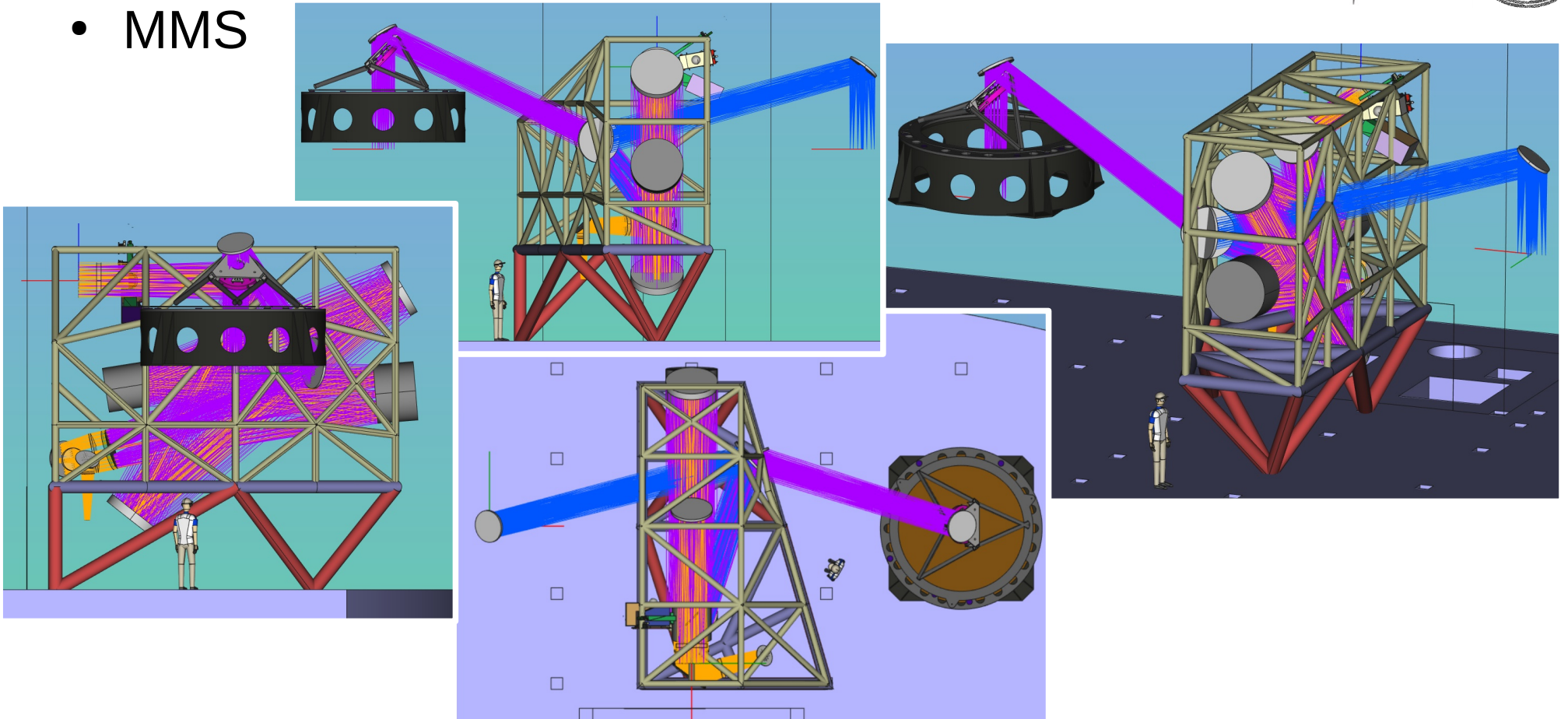
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MAORY Optical Design History



- MMS



MAORY Optical Design Comparison



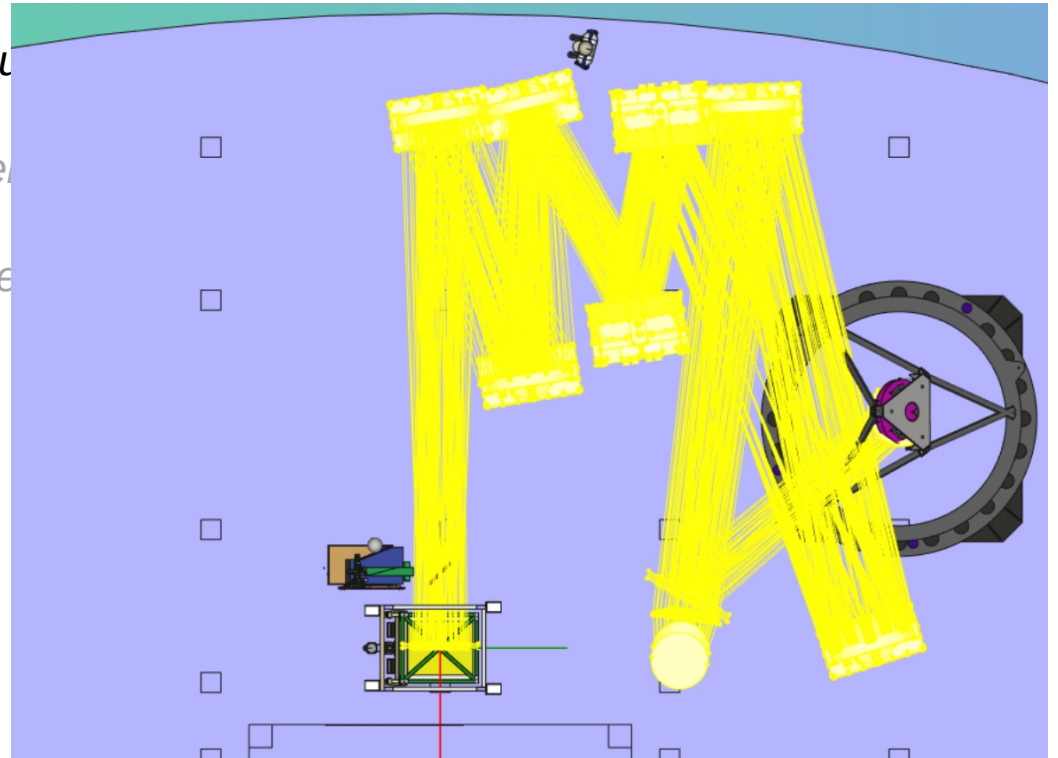
- **AMC** : *Original design up to November 2018*
- **MOC** : *Design presented to ESO in Ju*
- **miniMOC** : *Design evolution for we*
- **MMS** : *Design proposed by ESO in se
february 2020*



MAORY Optical Design Comparison



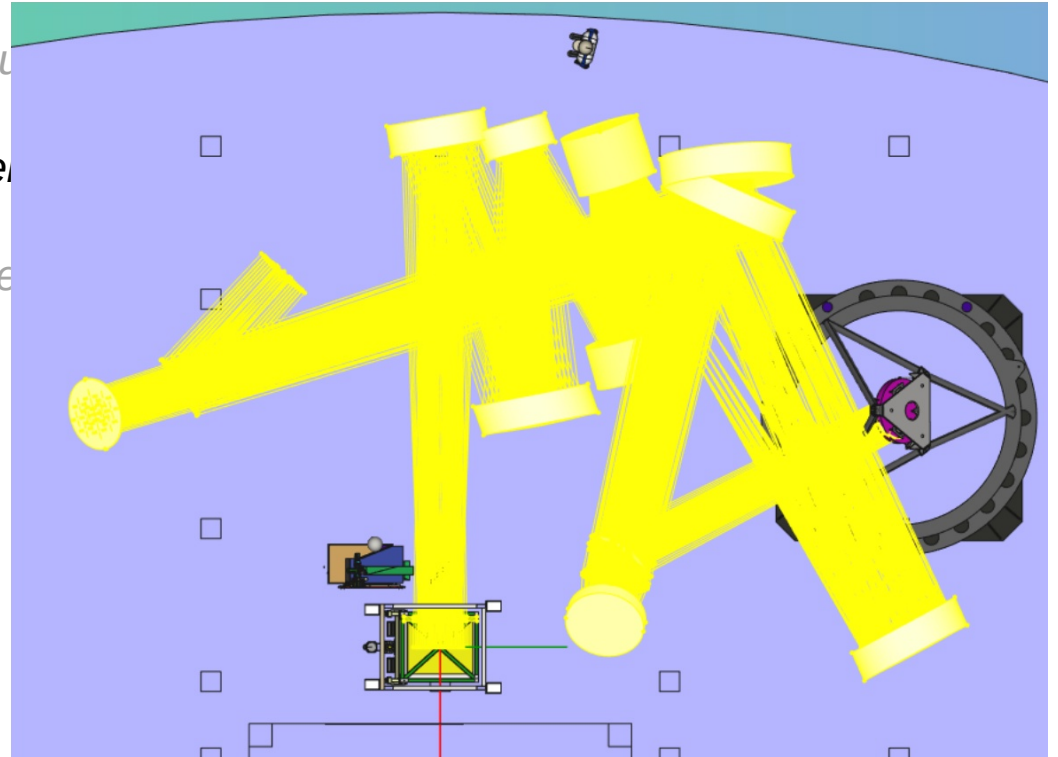
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MAORY Optical Design Comparison



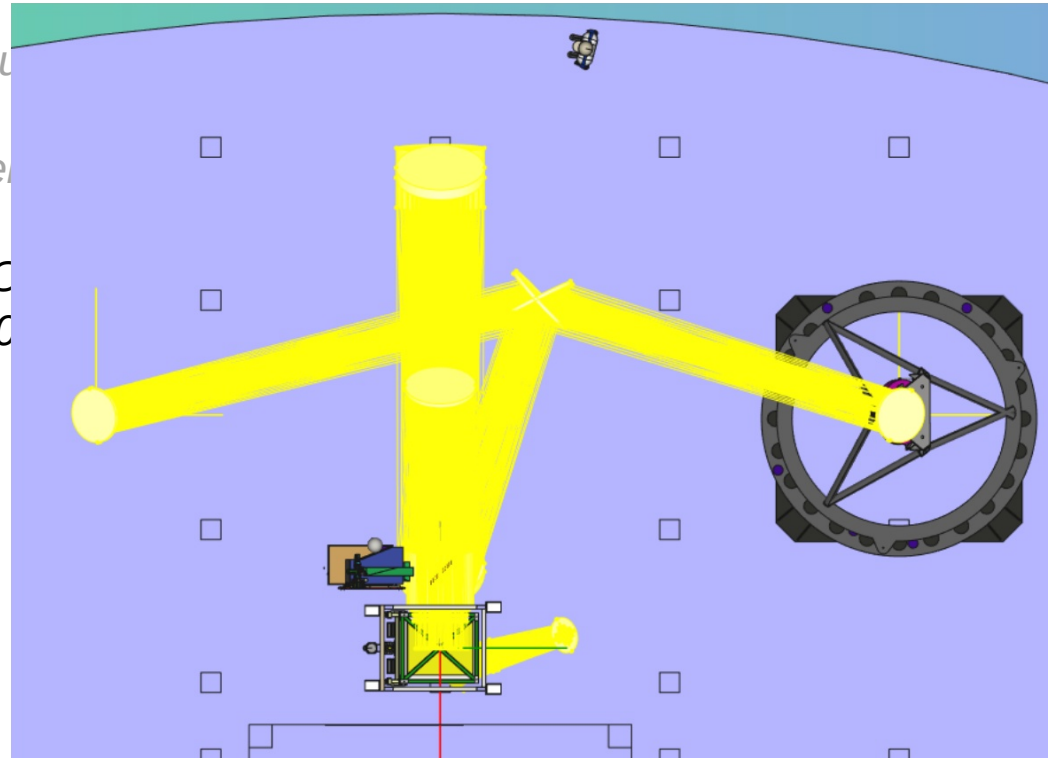
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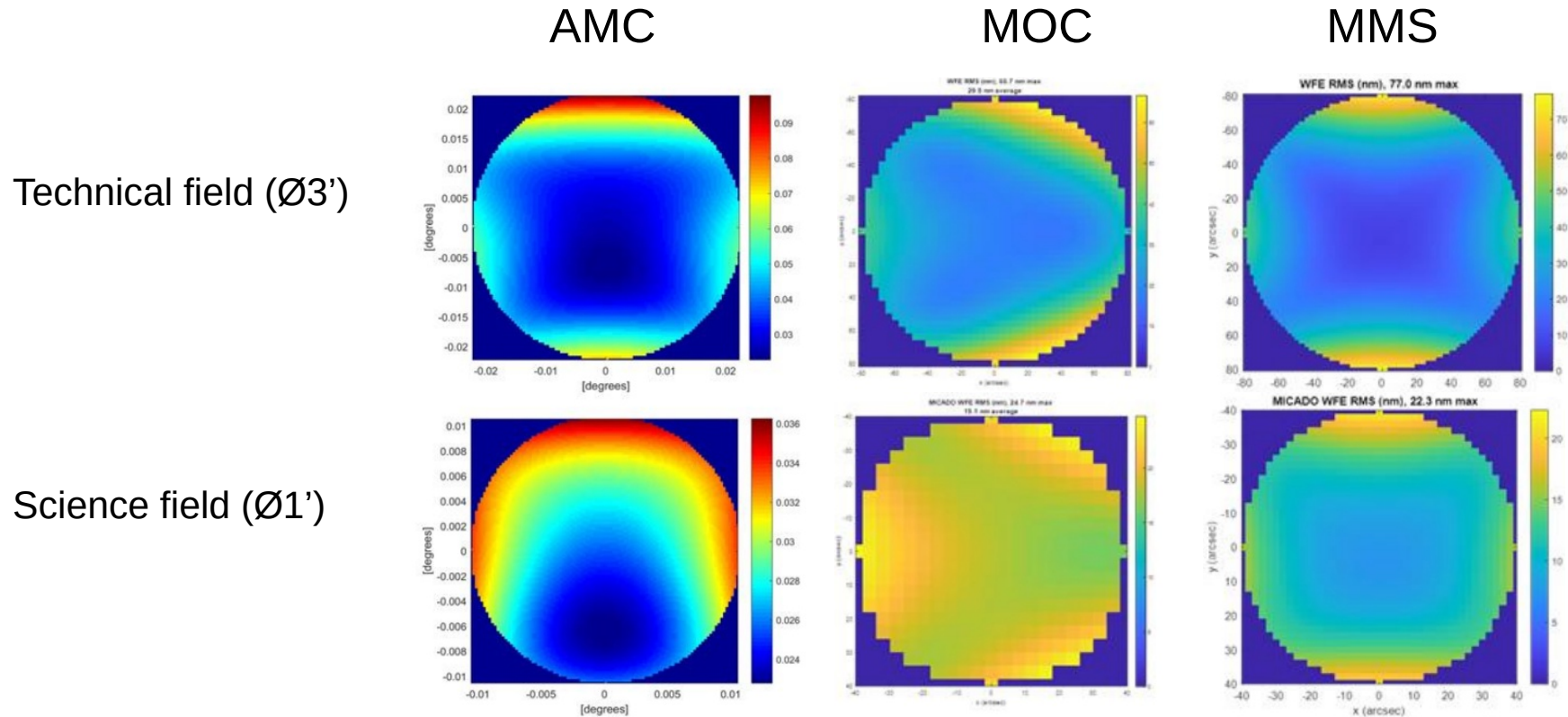
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MAORY Optical Design Comparison



- Wave-front error maps:



MAORY Optical Design Summary



SUMMARY:	ELT Nasmyth	AMC	miniMOC (MOC)	MMS
Plate-scale	3.316	1:1	1:1	1:1
Distortion (mas)		23.2	10.2	43
Distorsion variation (mas) req. <3		1.0	0.19	0.26
WFE science field (nm rms) req. <40		35	32	25
WFE technical field (nm rms) req. <120		90	75	75
Field curvature (m)	9.884	∞	9.283 (9.496)	∞
Numerical aperture	f/17.75	f/17.75	f/17.46	f/17.76
Pupil distance (m)	37.868	9.128	27.1 (25.513)	14.0
Pupil size (mm)	2134	514	1566 (1461)	788
Number of optics		7 reflections	9 reflections + plate	8 reflections + plate
Aspheric surfaces		5	1 mirror + plate	2 mirrors + plate
Max size of optics (m)		≈1.00	≈1.25 (1.40)	≈1.15
DM shape		conic	flat	spherical
Conjugate altitude (km)		4.3 & 15.0	6.9 & 16.0	6.9 & 17.5
Size of LGS dichroic		≈700mm	≈1000mm	≈800mm
Number of LGS optics		5 lenses + 2 mirrors	4 lenses + 1 mirror	4 lenses + 2 mirrors

MAORY Optical Design Summary

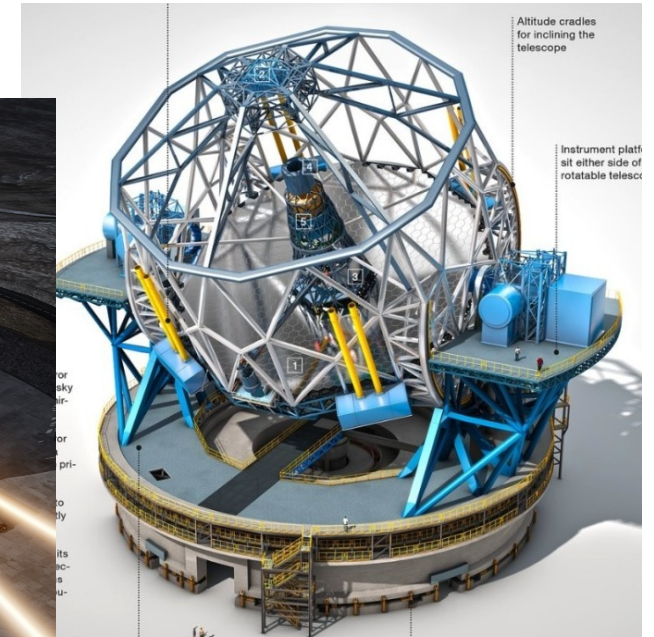
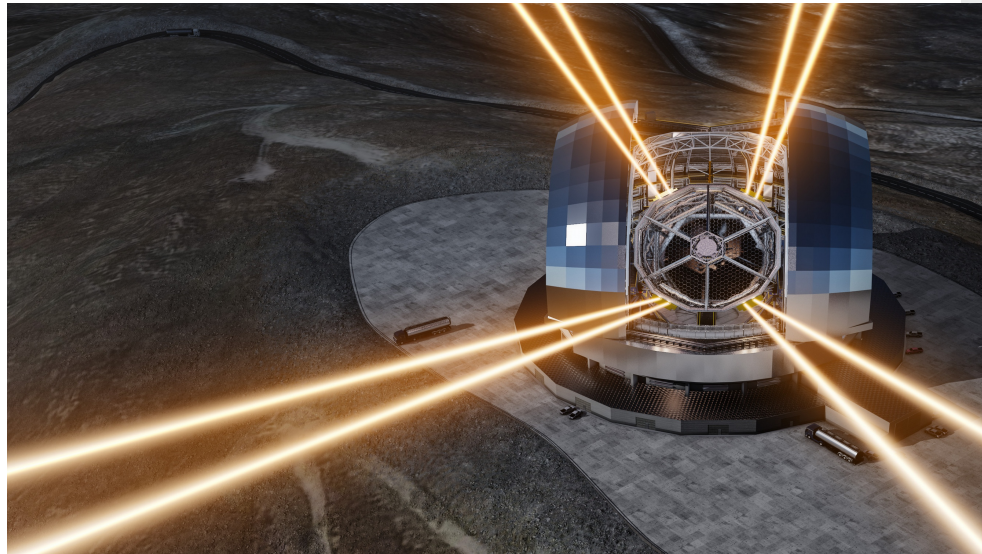


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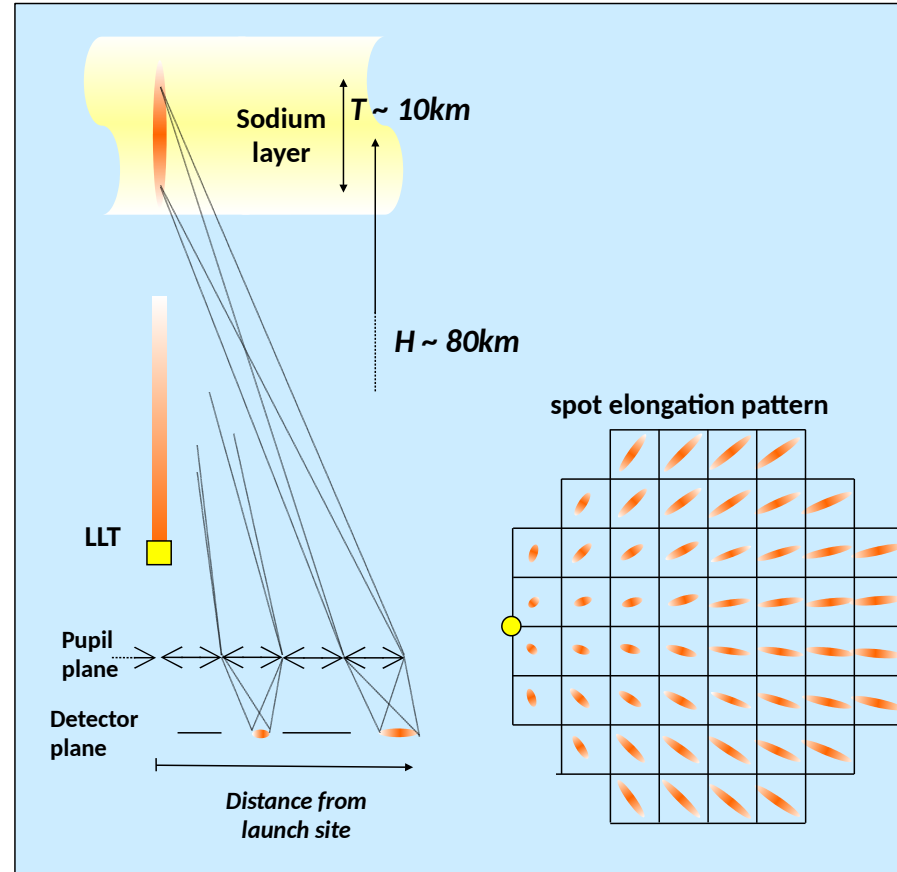
LGS-WFS subsystem



- Requirements:
 - 6 or 8 LGS-WFS
 - ELT elevation from 1.5° to 60°
 - Side launch

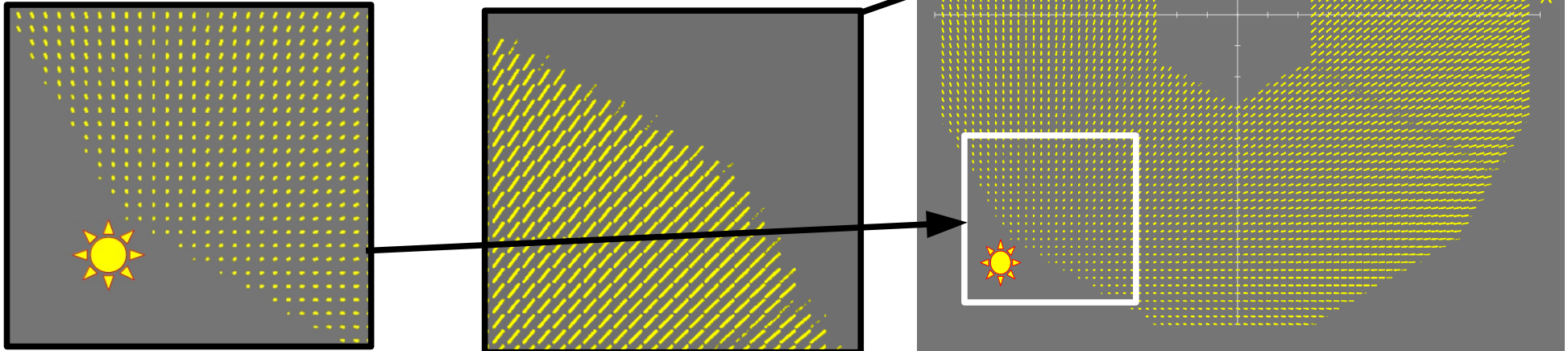


- Requirements:
 - 6 or 8 LGS-WFS
 - ELT elevation from 1.5° to 60°
 - Side launch
 - Spot elongation:
 - Sodium layer at finite distance



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LGS-WFS subsystem



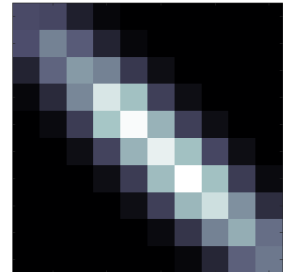
- Requirements:

- 6 or 8 LGS-WFS
- ELT elevation from 1.5° to 60°
- Spot elongation:
 - Sodium layer at finite distance
 - Side-launch
 - Spot size ≈ 1 arcsec
- To avoid truncature: field stop ≈ 15 arcsec (simulated: 10, 15, 20)

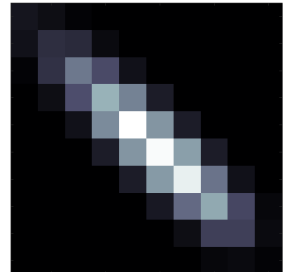
- Configurations:

LISA LVSM detector 800×800, 24μm px	Sony IMX425 detector 1100×1604, 9μm
80sp × 10px = 800px	84sp × 13px = 1092px
66sp × 12px = 792px	78sp × 14px = 1092px
57sp × 14px = 798px	68sp × 16px = 1088px

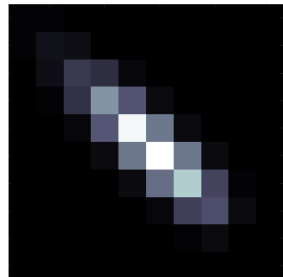
Field-stop 10''



Field-stop 15''

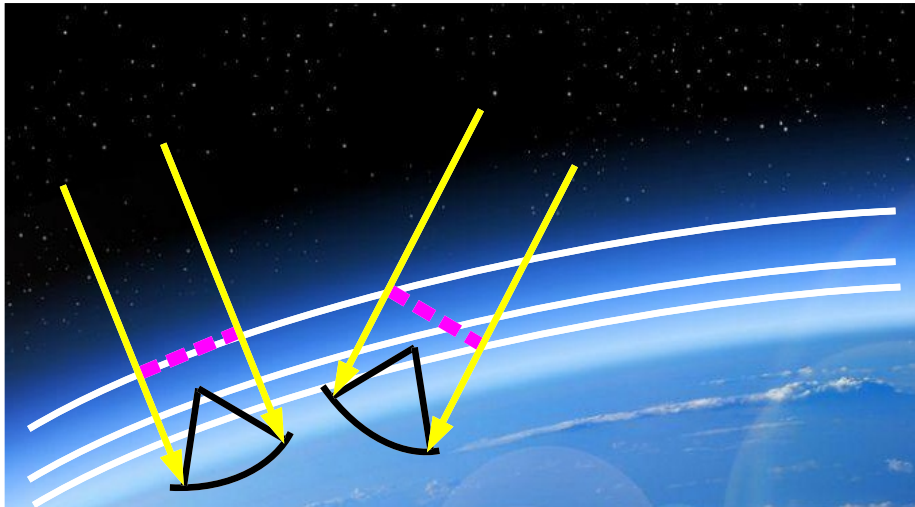


Field-stop 20''



- Requirements:

- 6 or 8 LGS-WFS
- ELT elevation from 1.5° to 60°
 - Focus follows ELT elevation: with sodium layer at 85km, distance to sodium layer from 85km to 160km



- Requirements:

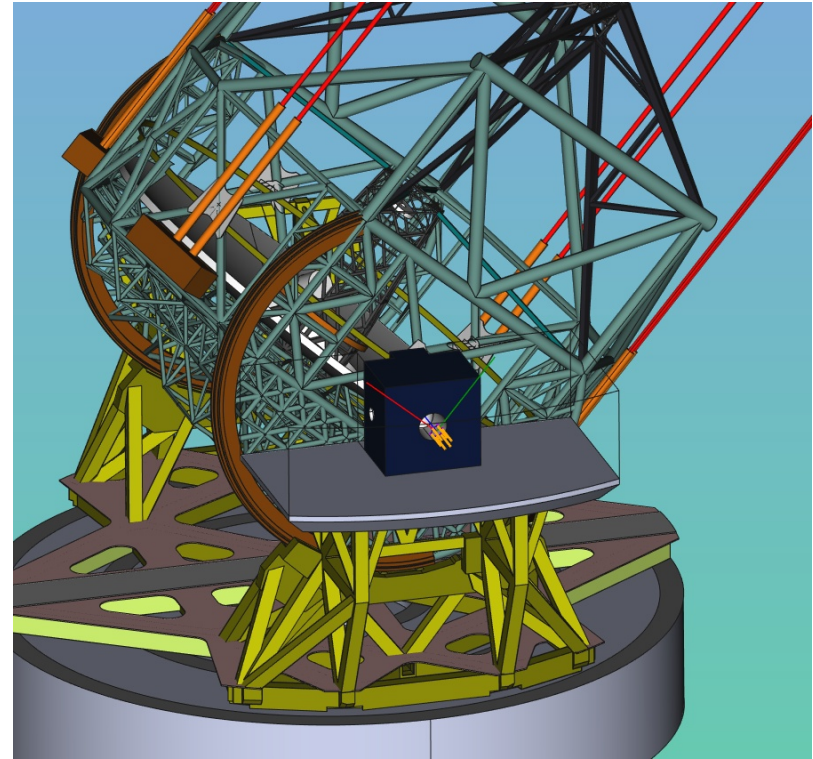
- 6 or 8 LGS-WFS
- ELT elevation from 1.5° to 60°
 - Focus follows ELT elevation: with sodium layer at 85km, distance to sodium layer from 85km to 160km
 - $\Delta\text{focus}_{\text{LGS}/\infty} = 2.493\text{m} - 6.914\text{m} = 4.421\text{m}$
 - Nasmyth f/17.75
 - LGS objective : f/5
 - $\Delta\text{focus}_{\text{LGS}} = 4.521\text{m} \times \left(\frac{5}{17.75}\right)^2 = 350\text{mm}$

Straight Through Focus (A1)	
Object at Infinity	-27200
Laser Beacon at 200km	-29693
Laser Beacon at 80km	-34114

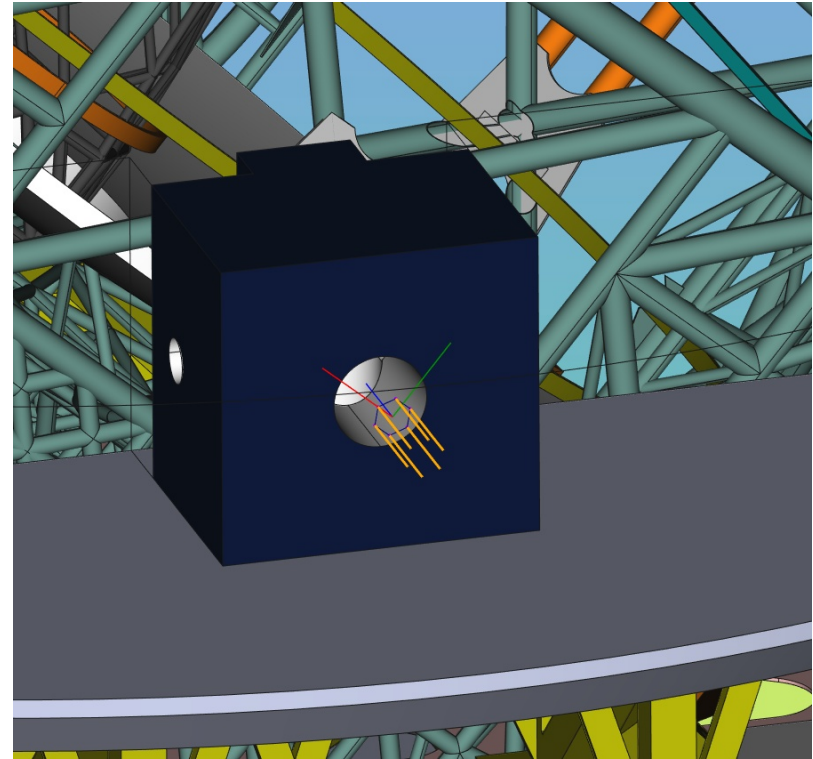
LGS-WFS subsystem



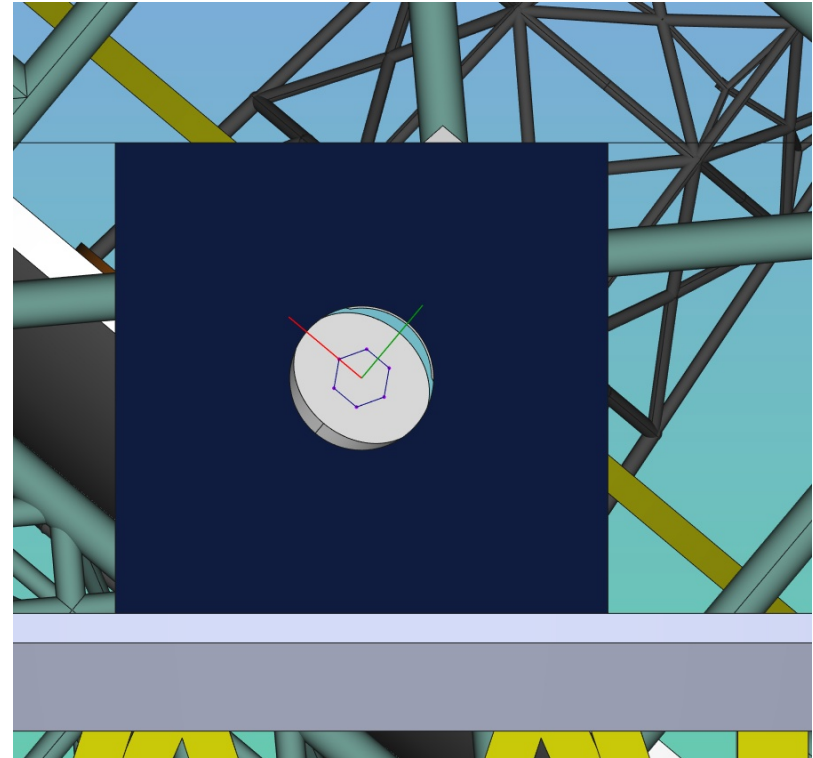
- Nasmyth LGS focus (LGS asterism constellation) rotates with ELT pupil (M1 & M4)
- Follows elevation
- For the LGS-WFS, a unique rotator follows focus **AND** pupil
- For NGS-WFS (like SCAO) MICADO derotates field + K-mirror derotates pupil



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- Requirements:

- 6 or 8 LGS-WFS
- ELT elevation from 1.5° to 60°
 - Focus follows ELT elevation: with sodium layer at 85km, distance to sodium layer from 85km to 160km
 - $\Delta\text{focus}_{\text{LGS}} = 350\text{mm}$
 - Max speed: 5mm/s (max 60s between target pointings)
 - LLT attached to ELT M1, M4 and M1 rotate together: LGS constellation follows M1 rotation:
 - $\Delta\text{rotation} = 60^\circ$
 - For maintenance we plan 360° , cables detached
 - Max speed: $1^\circ/\text{s}$ (max 60s between target pointings)

LGS-WFS Requirements



- Tech Spec rotation:

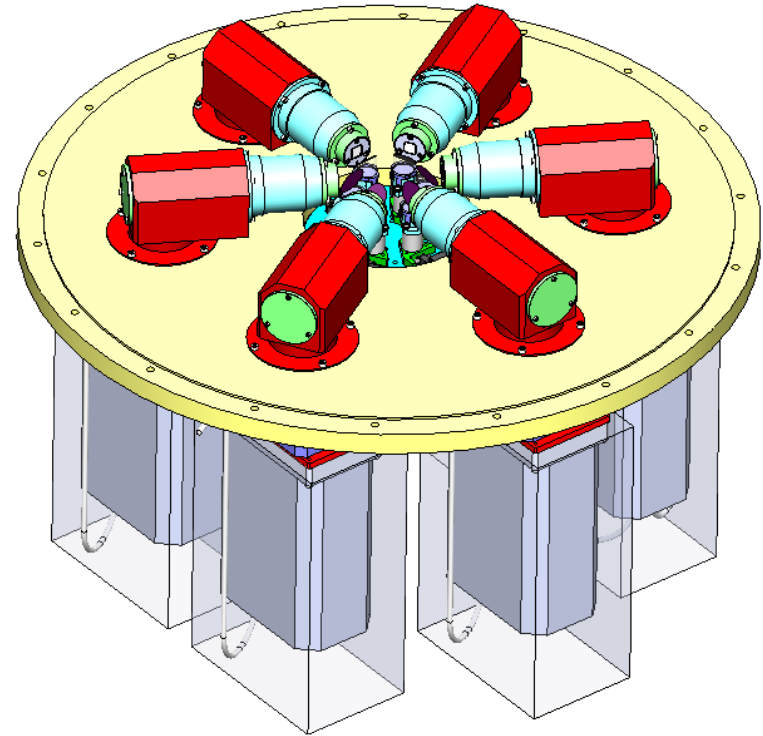
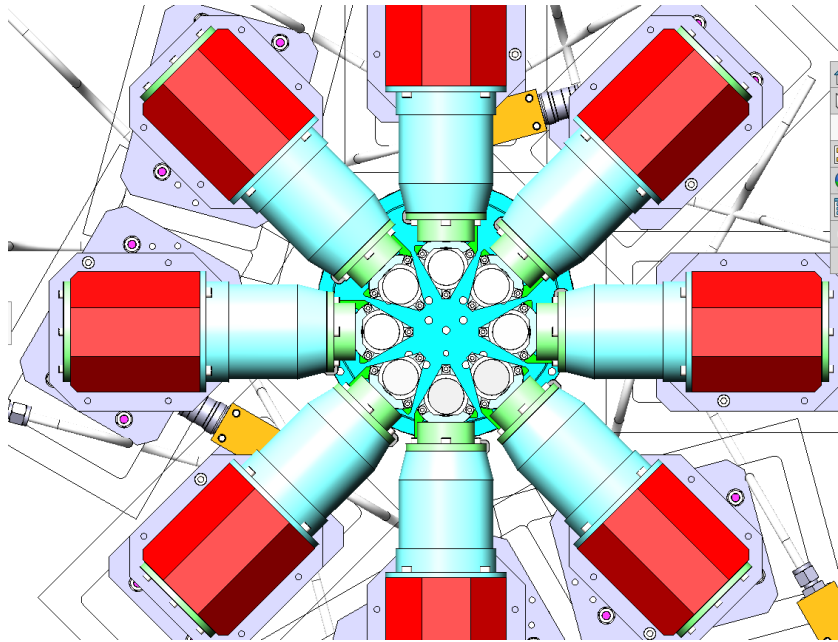
- Max speed: $1^\circ/\text{s} = 1 \text{ min}$ for full 60° change $\rightarrow 1 \text{ min}$ for presets
- Acceleration $0.1^\circ/\text{s}^2$
- Max range in operation 70°
 - Free rotation for AIT and maintenance (without cables): 360°
- Wobble: *The wobble over any 90° rotation shall be less than 0.02° or 1 arcmin*
- Run-out: *The runout over any 90° rotation shall be less than $\pm 50\mu\text{m}$*
- Performance:

	Observation	Between 2 observations	Maintenance
Max angle	70° (TBC)	70°	360°
Speed	Max $1^\circ/\text{s}$ – Min \approx	$1^\circ/\text{s}$	Req: $1^\circ/\text{s}$ Goal: $10^\circ/\text{s}$
Resolution	Req: $10''$ Goal: $2''$	NA	NA
Precision	Req: $40''$ Goal: $20''$	Req: $40''$ Goal: $20''$	



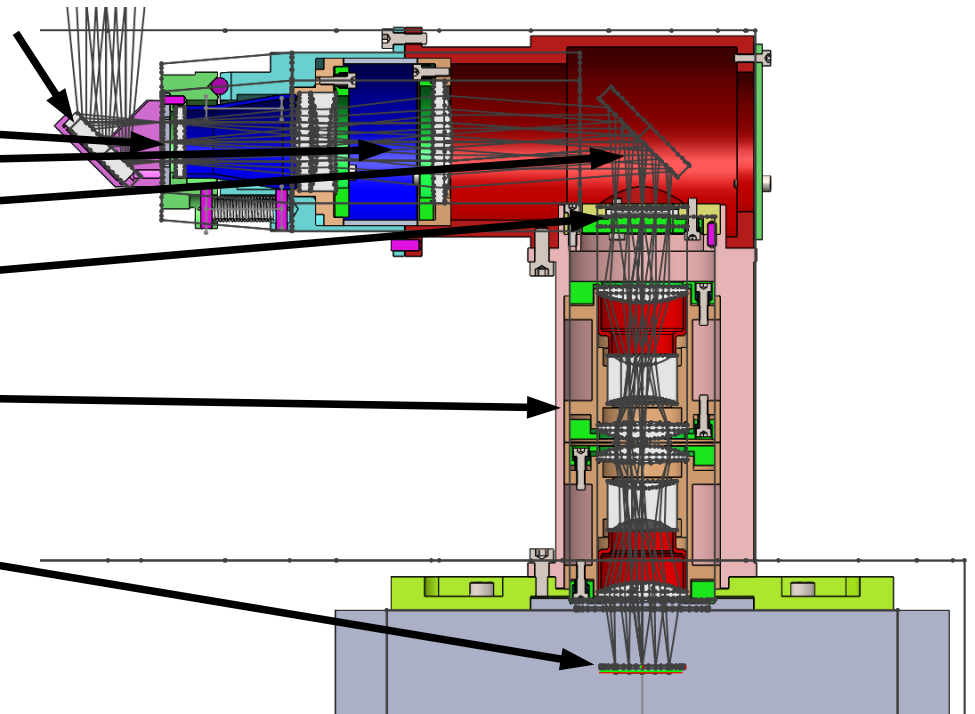
- Tech Spec alignment:
 - Θ - φ of derotator :
 - $\Delta\text{pupil} < 0.5\%$
 - Θ - φ of translation :
 - $\Delta X_{\text{focus}} < 0.1''$ ($\sim 1/10^{\text{th}}$ pixel)
 - With platescale $1'' = 1\text{mm}$ → 0.1mm ($100\mu\text{m}$)
 - X-Y of entire module :
 - $\Delta X_{\text{focus}} < 0.1''$ ($\sim 1/10^{\text{th}}$ pixel)
 - With platescale $1'' = 1\text{mm}$ → 0.1mm ($100\mu\text{m}$)

- 6 (or 8) identical channels:
 - IPAG provides them also for HARMONI

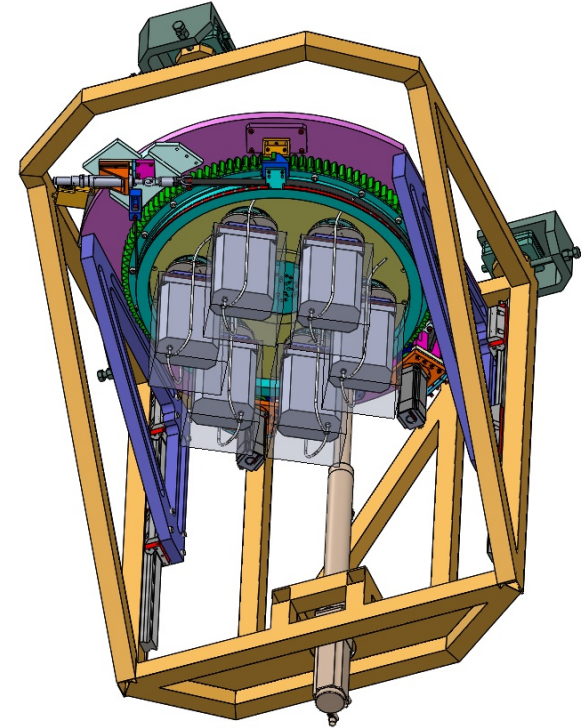
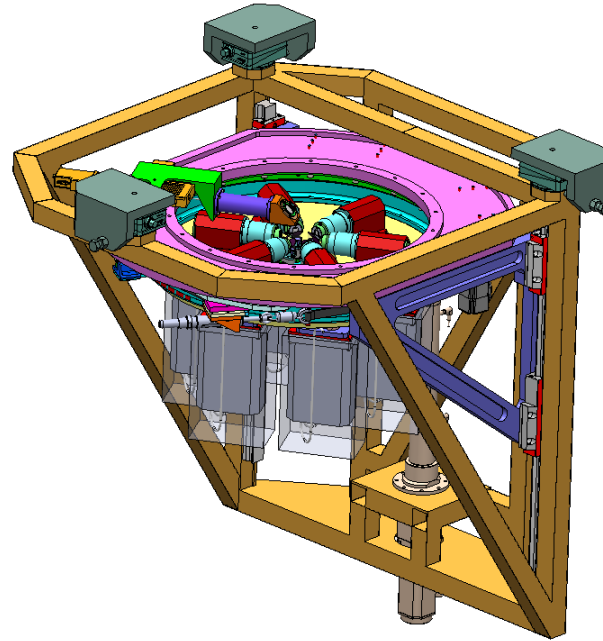
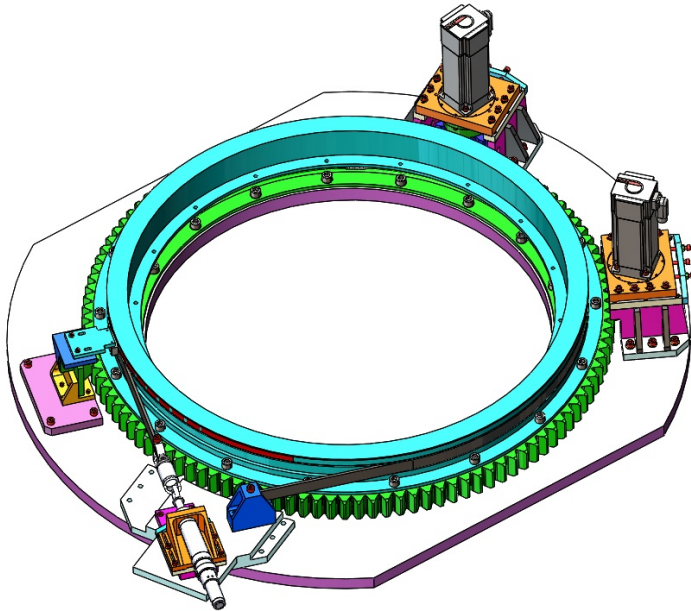


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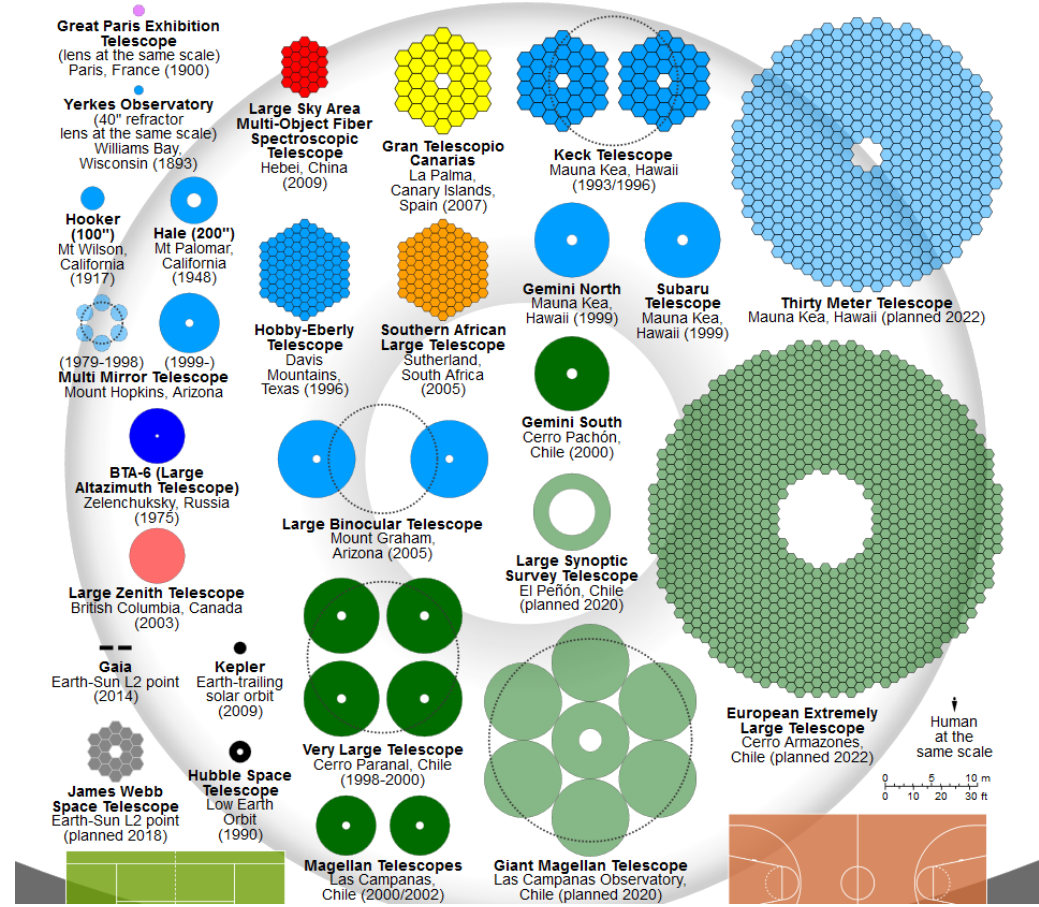
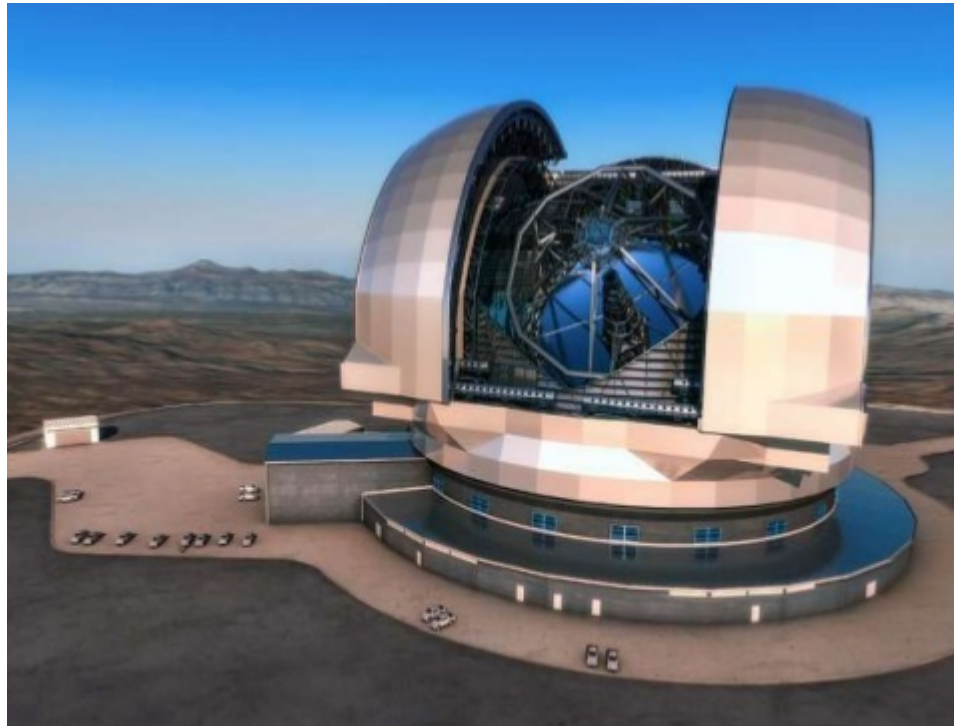
- Pick-off mirror (piezo, pupil steering mirror)
- Field-stop
- Collimator
- Fix 45° mirror
- Lenslet array
- Relay optics
- Detector



- 6 (or 8) identical channels:
 - Derotator: MPIA-inspired



Thank-you for your attention



Appendix

